

Computational color



ITÄ-SUOMEN YLIOPISTO

Two main topics in this course

- How to represent color as device independent
 - how to produce device independent color representation from device dependent color representation
- How to represent accurate color spectrum information
 - how to compress the high dimensional spectral information into a low dimensional approximation
 - how to reconstruct accurate spectral information from a low dimensional color representation



Study forms in the course

- lectures: Wednesday 10 - 12 and Friday 10 - 12
- home exercises, "theoretical problems"
- practical exercises, testing the studied methods by using real spectral sets and spectral images

- Final exam

- lectures Professor Jussi Parkkinen
- exercises researcher Ville Heikkinen
 researcher Alexey Andriyashin



Form and color are important in object recognition

How do you separate the peppers from each other?



What is Color?

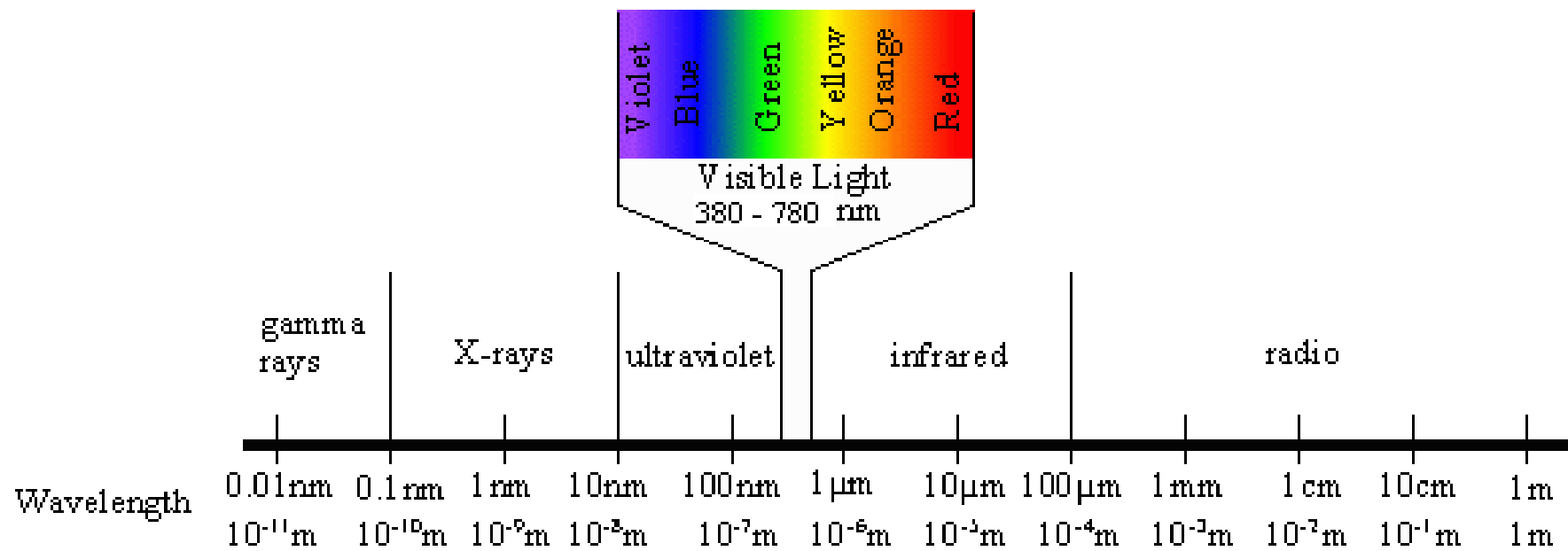
i.e. what are the goals in previous slide?

- “Color is what human see” - colorimetric approach
 - color is represented by RGB, $L^*a^*b^*$, etc.
 - wavelength range limited by human visual system
- “Color is a property of an object and color information is carried in the color signal, electromagnetic radiation from object to detector” - photometric or physical approach
 - color is represented by color spectrum
 - not limited wavelength range

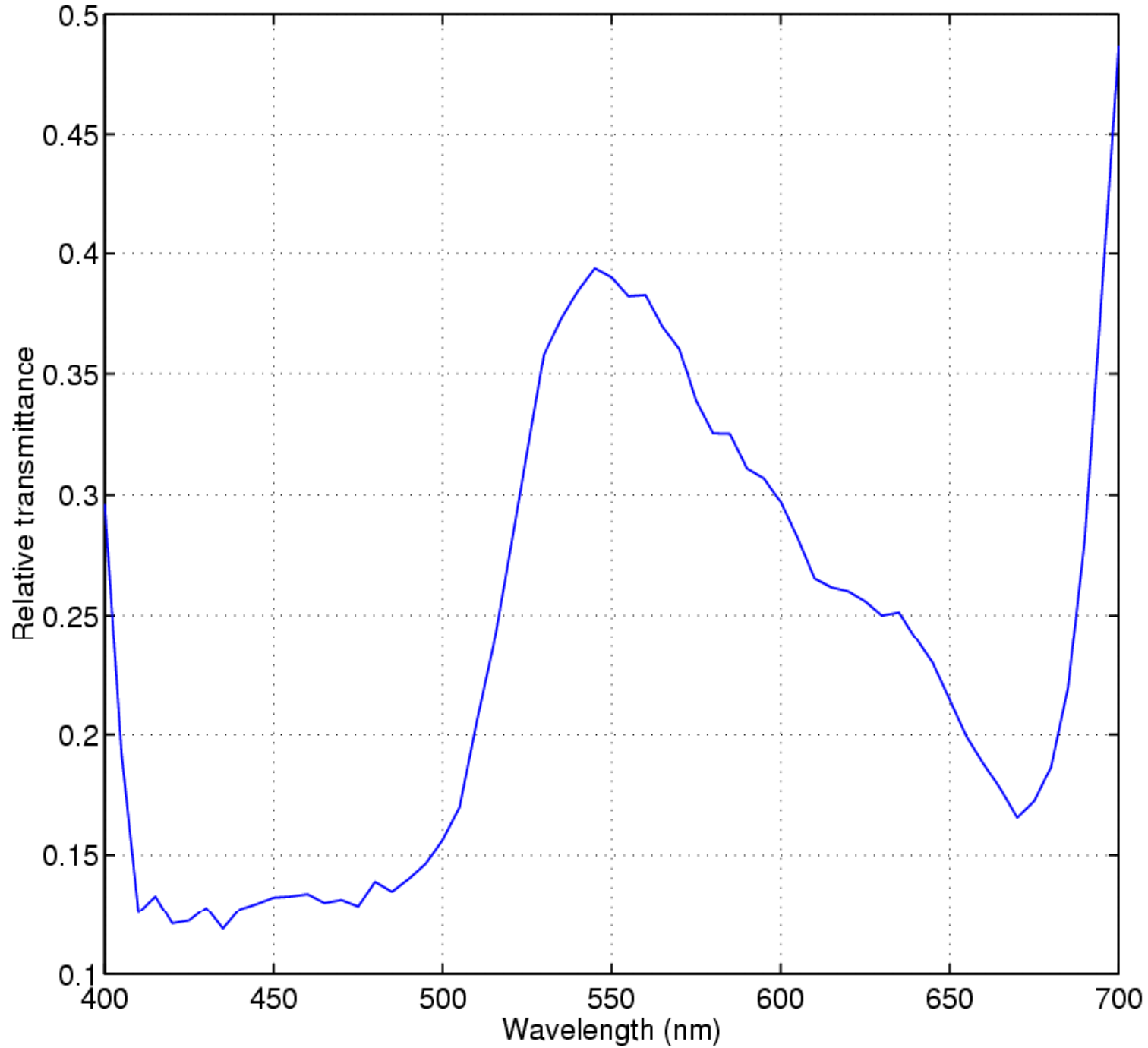
Approach in this course



The visible spectrum

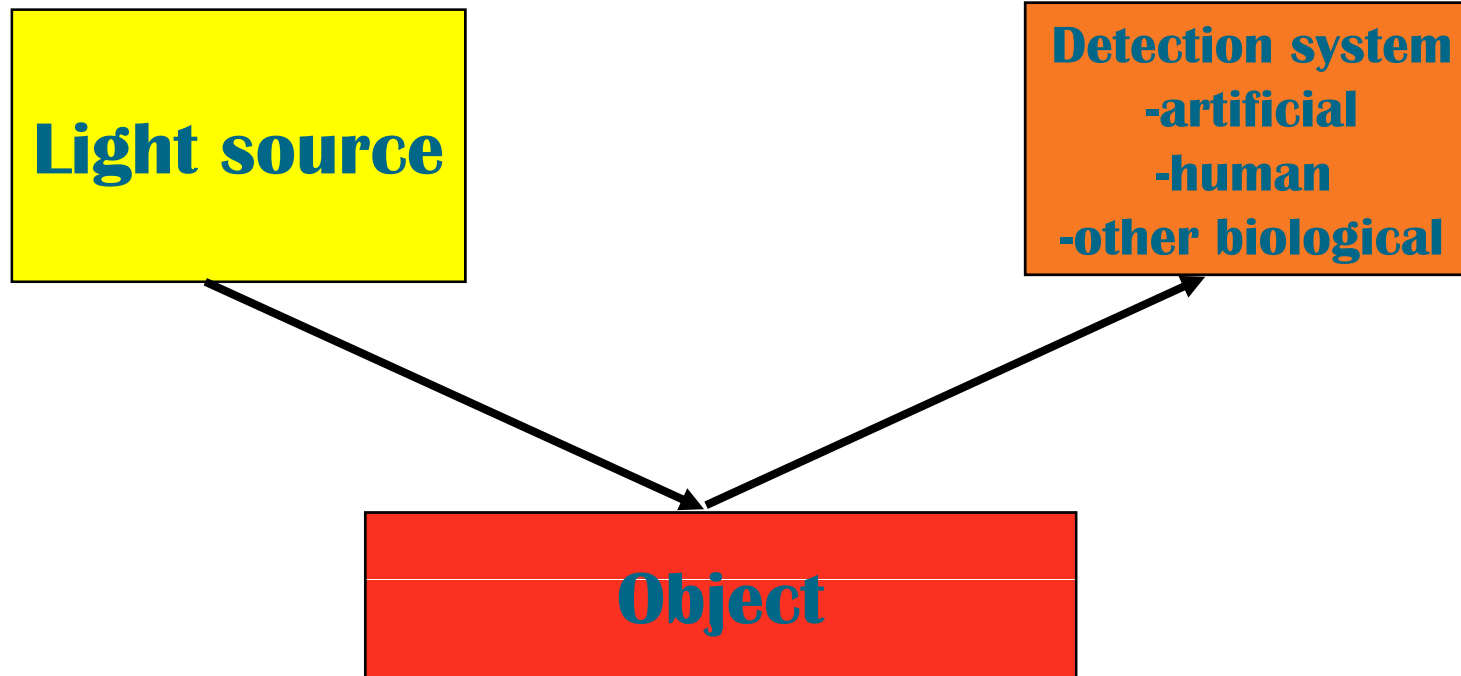


birch – green leaf

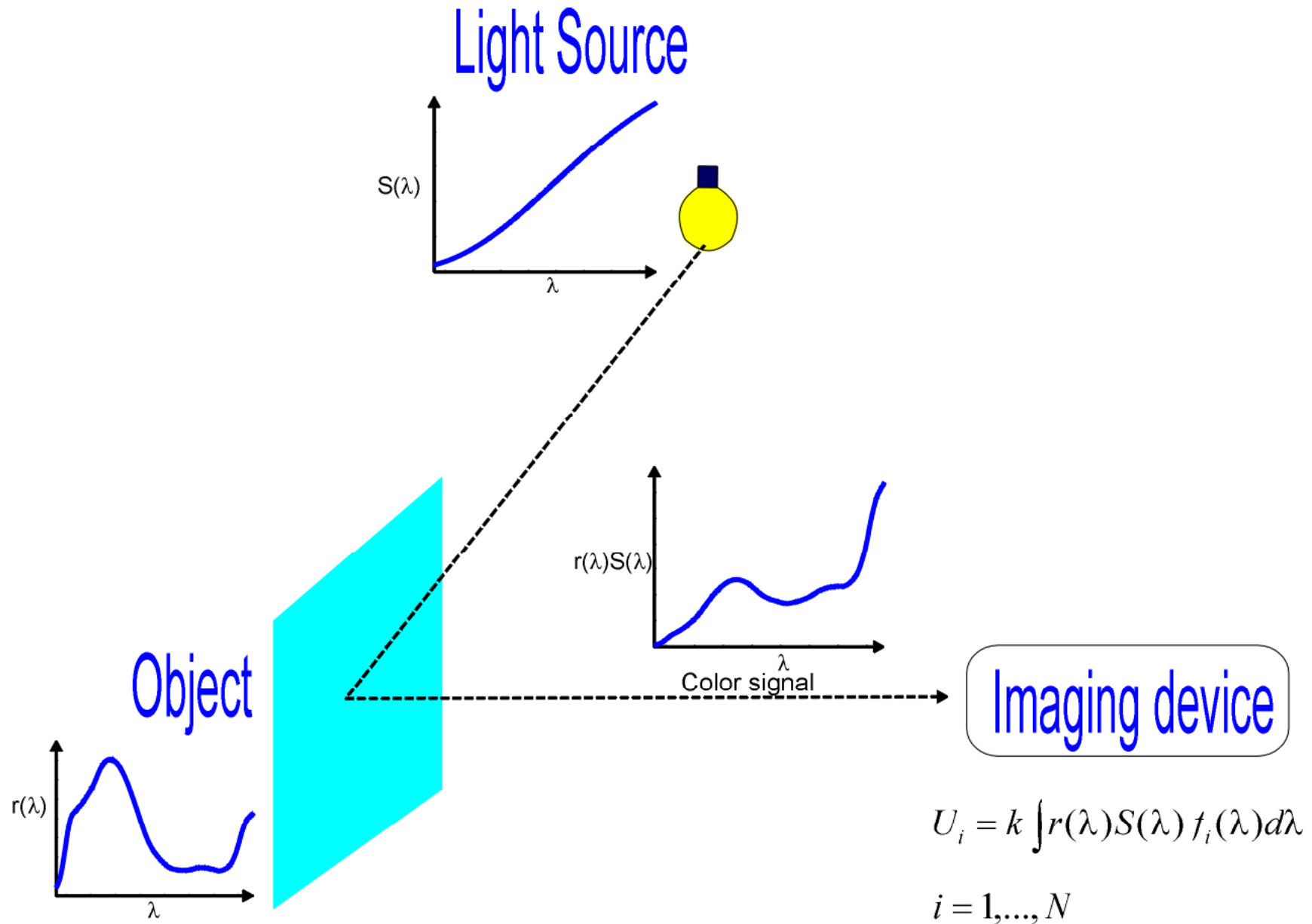


Our approach to color

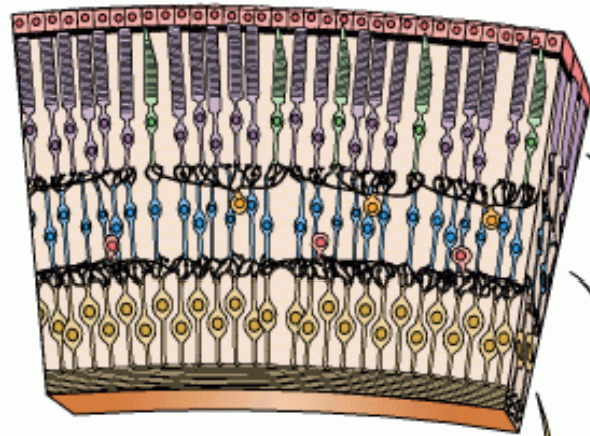
- Color information is carried by the light signal originated from the colored object
- This signal is measurable and unique



Formation of the Color Signal

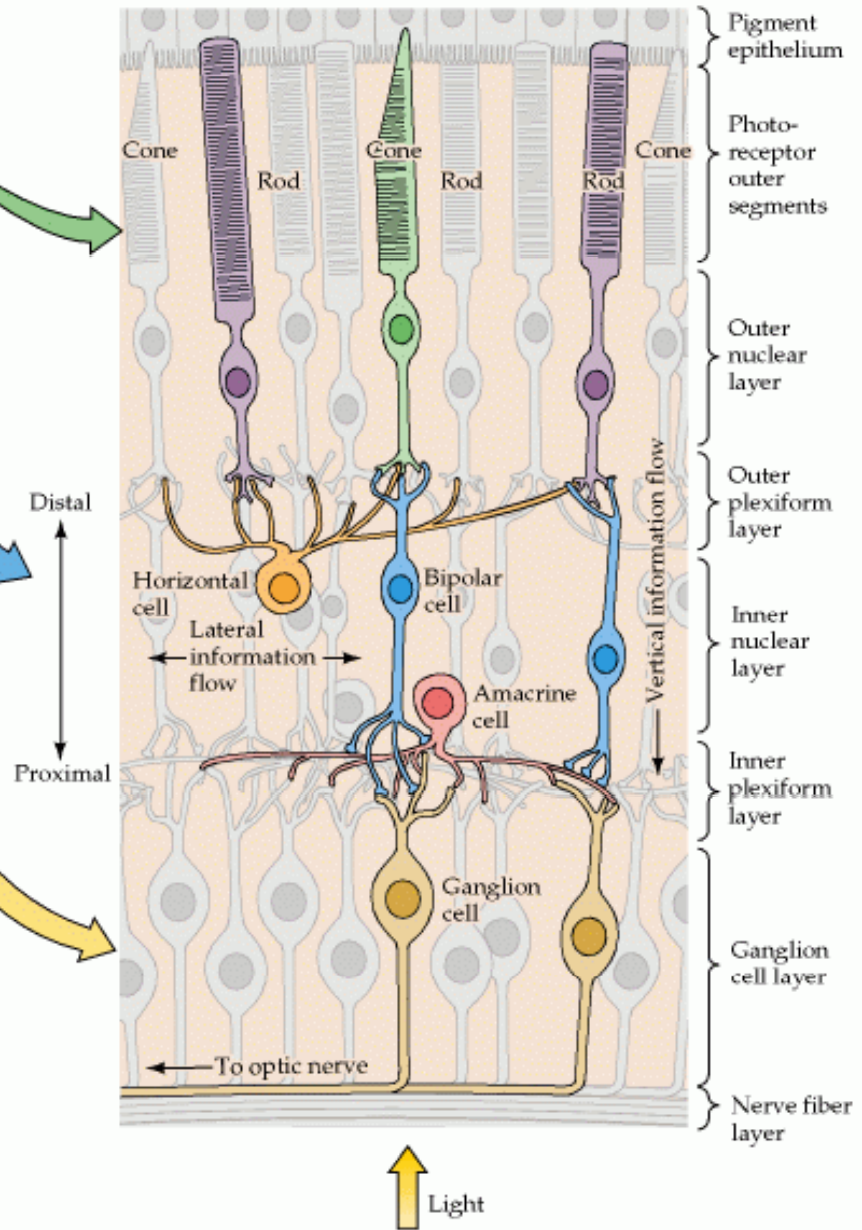


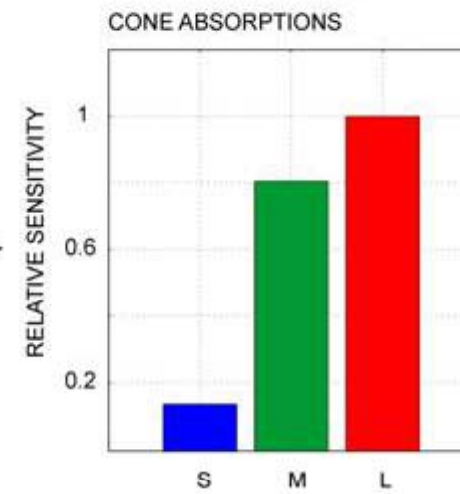
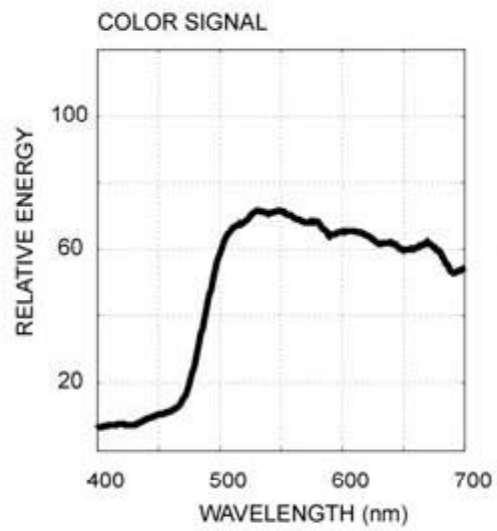
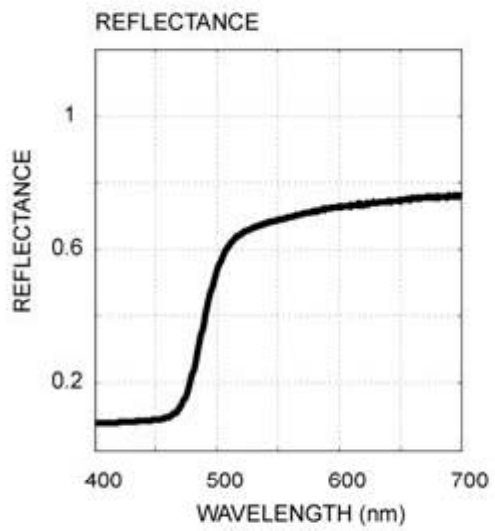
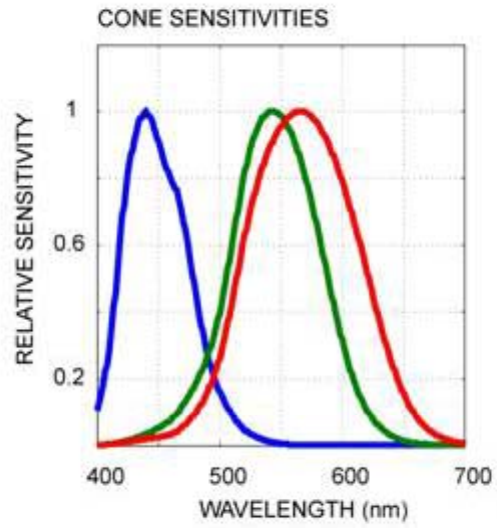
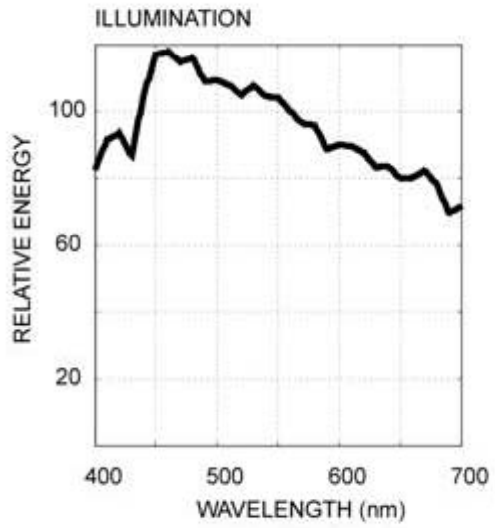
(A) Section of retina



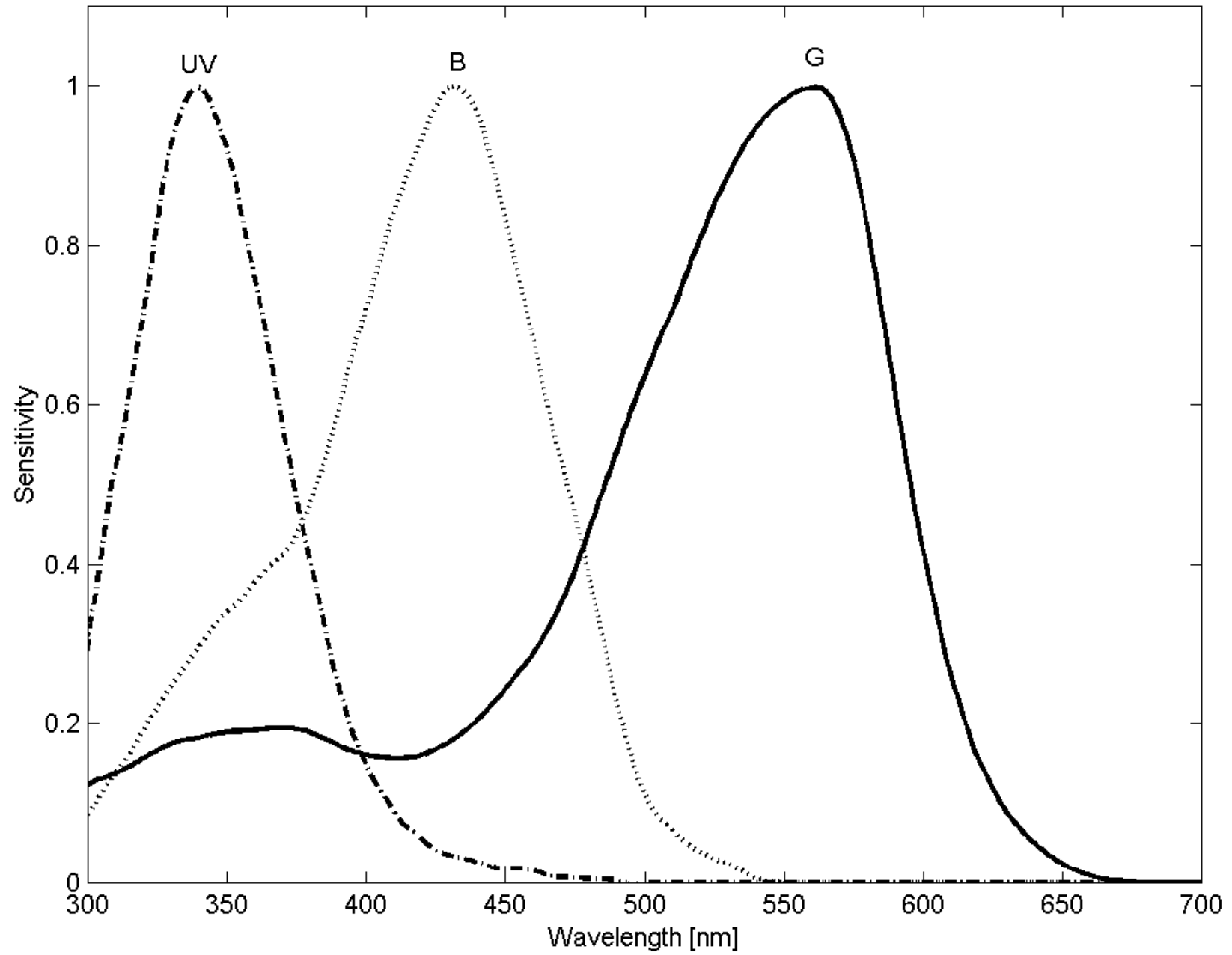
Light

(B)

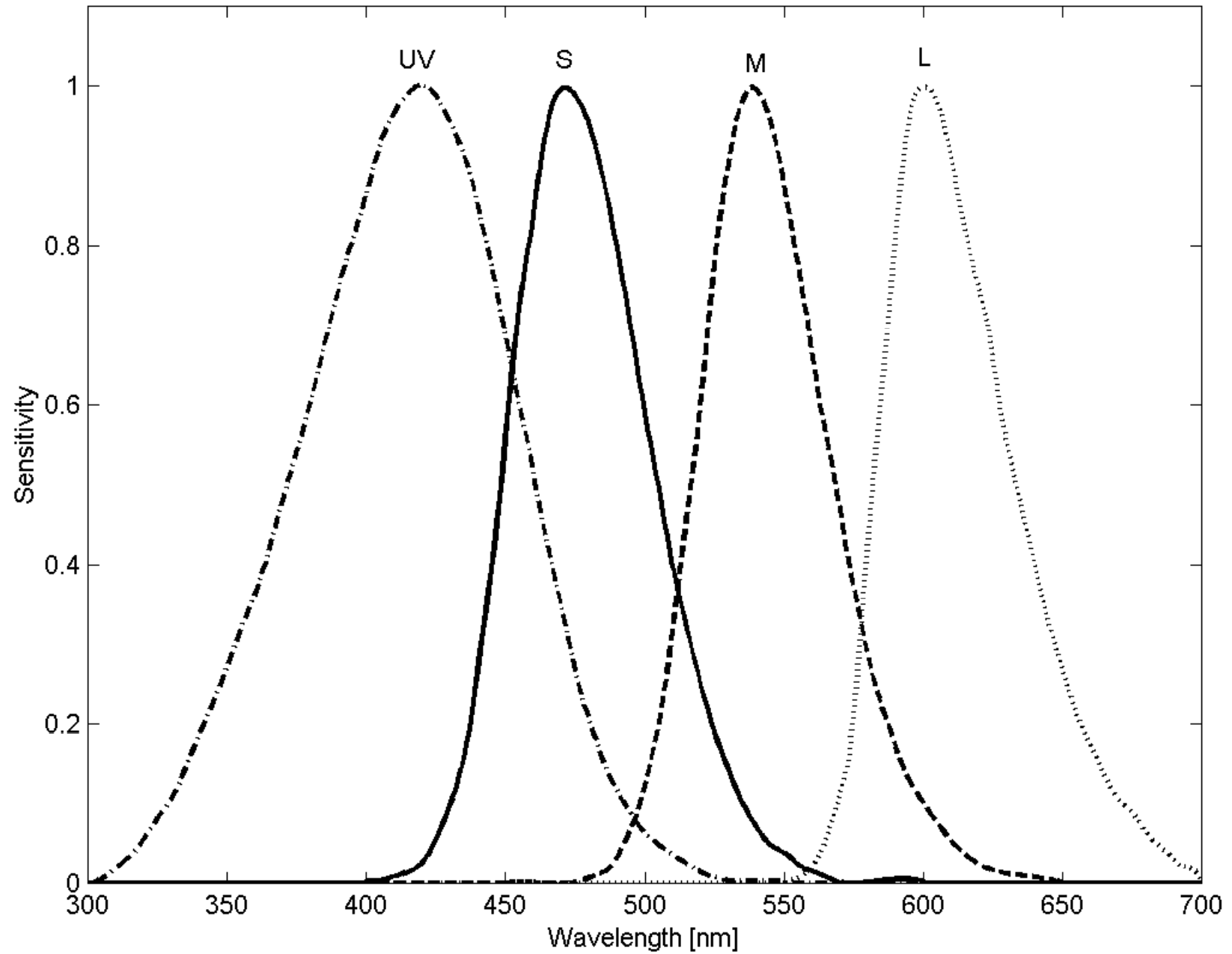




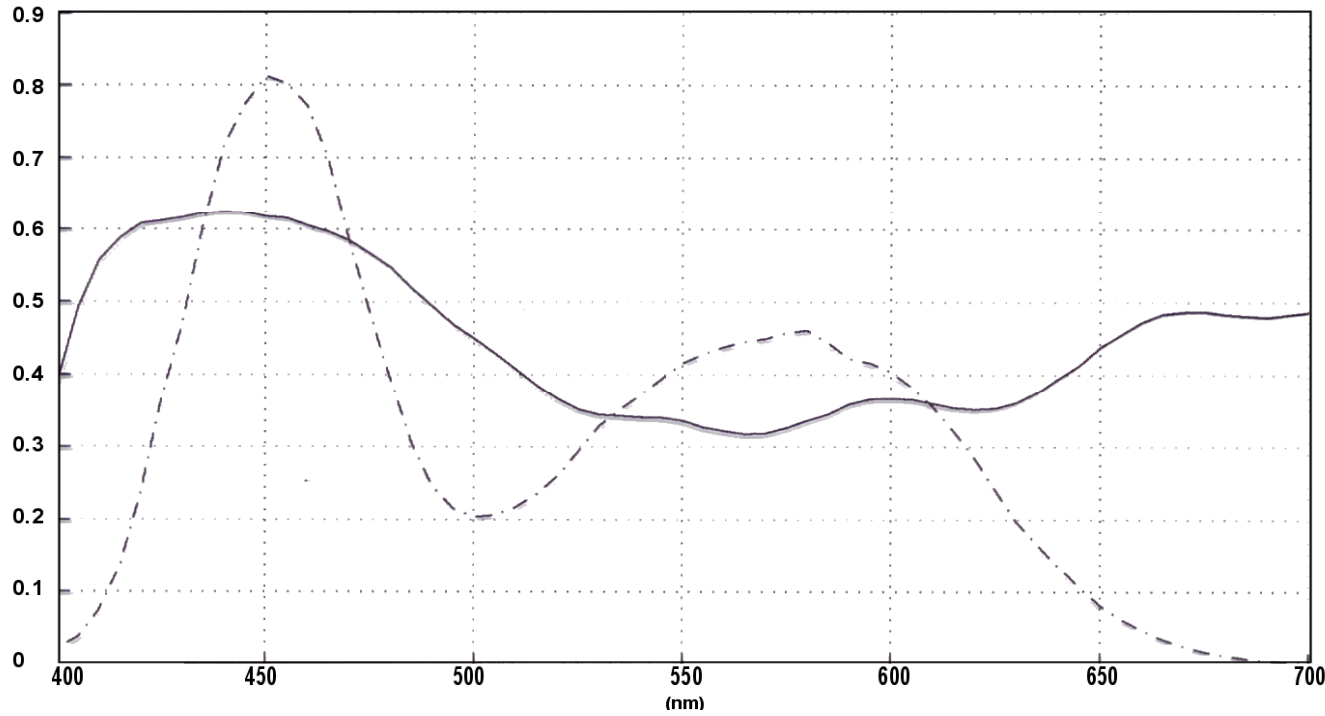
Spectral sensitivities of honeybee



Spectral sensitivities of chicken



Metamerism




L* 66.90
a* 11.94
b* -24.60




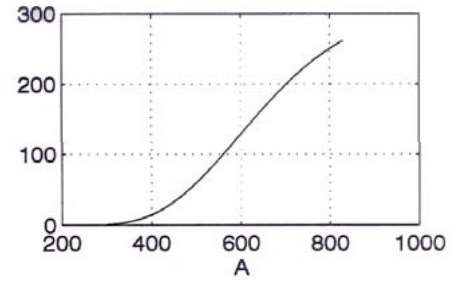
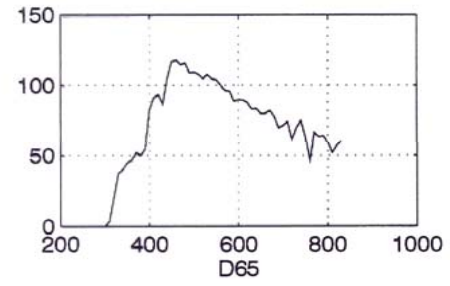
L* 66.90
a* 11.94
b* -24.60

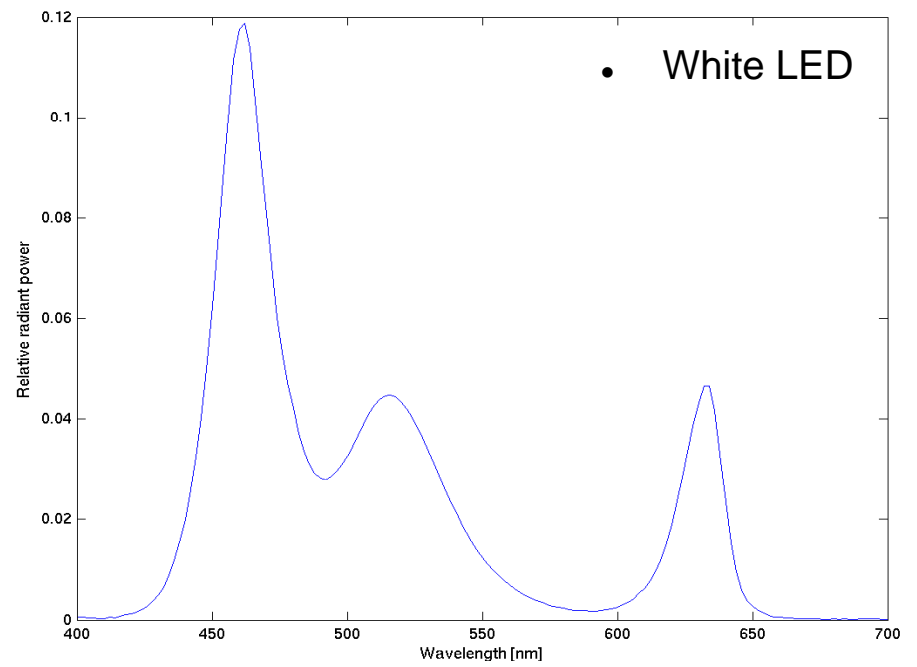
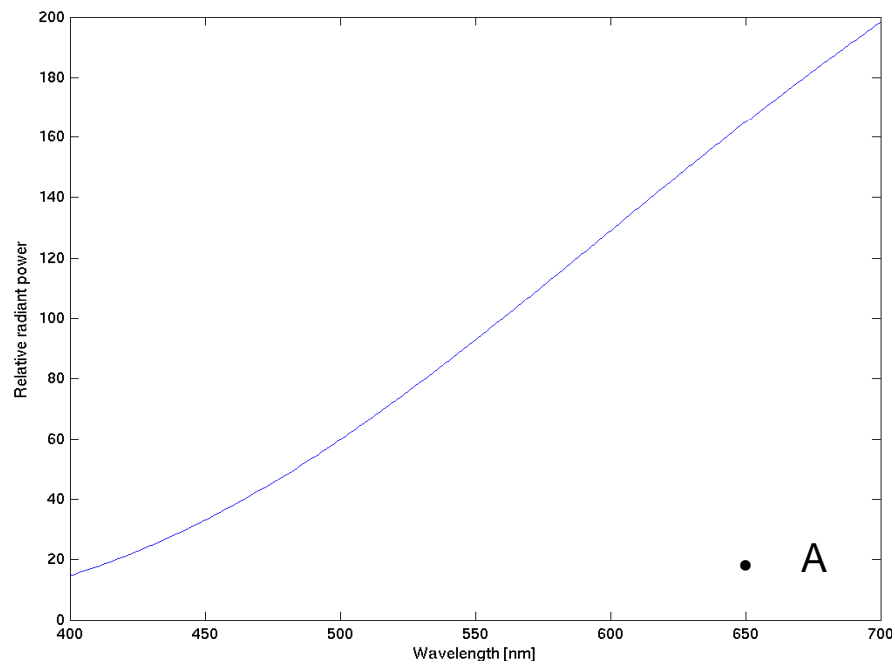
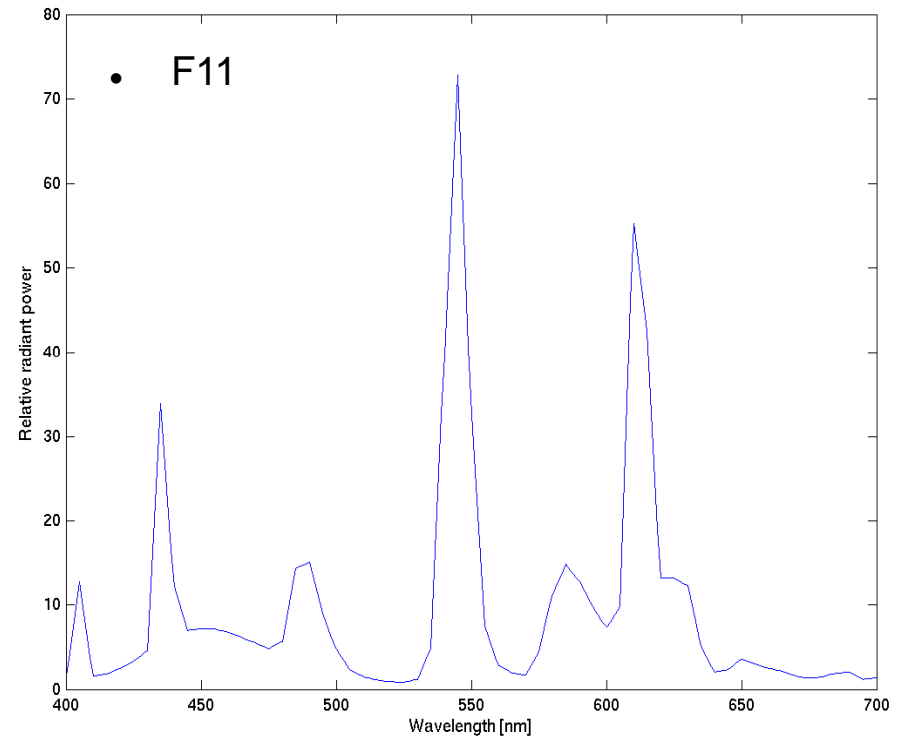
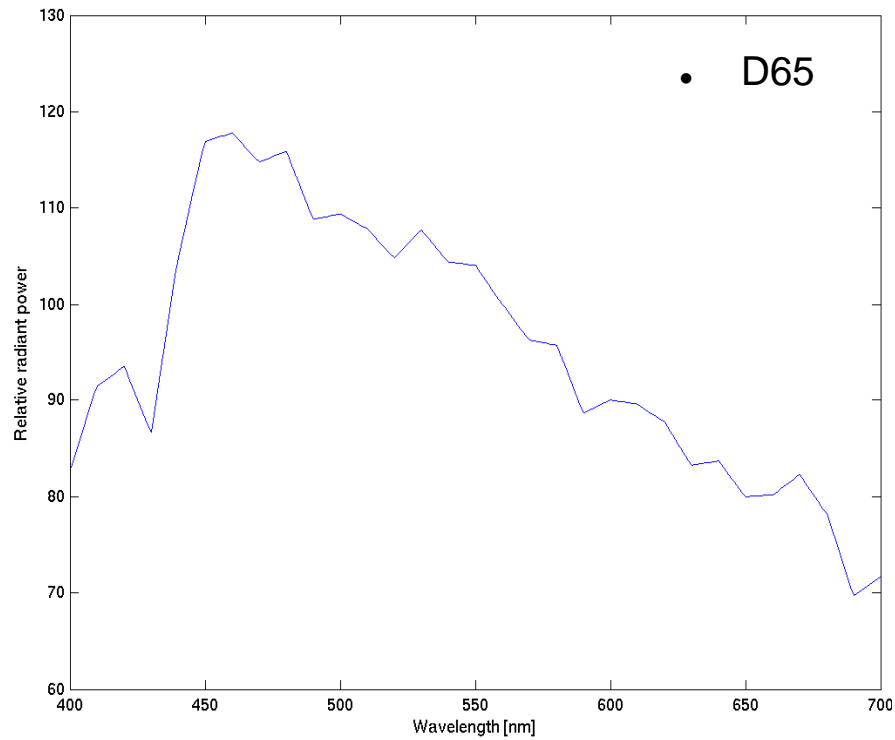


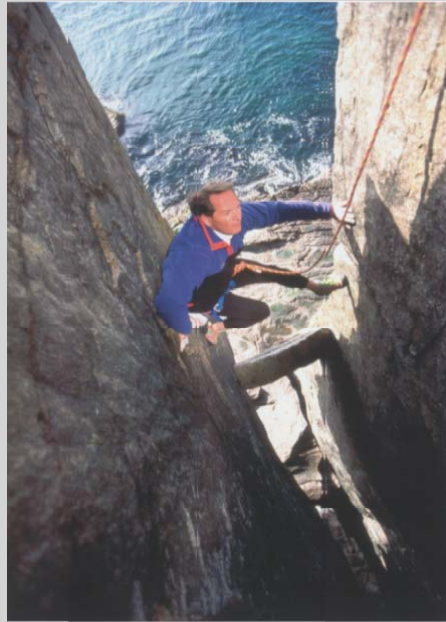

L* 66.37
a* 5.27
b* -24.16



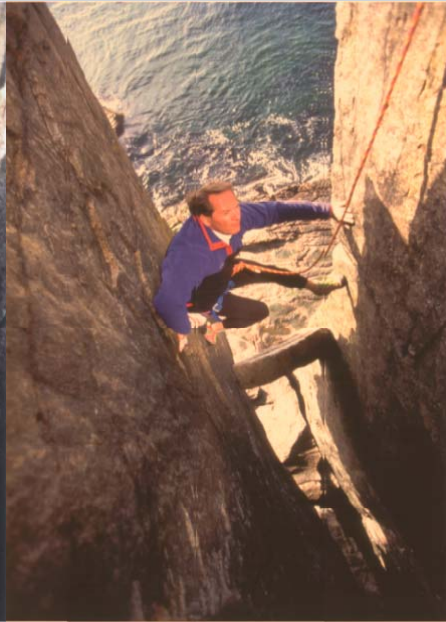
L* 66.51
a* -5.80
b* -22.84

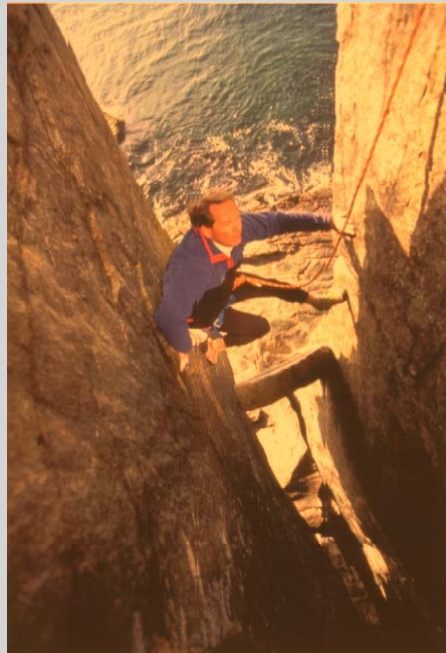




• D65



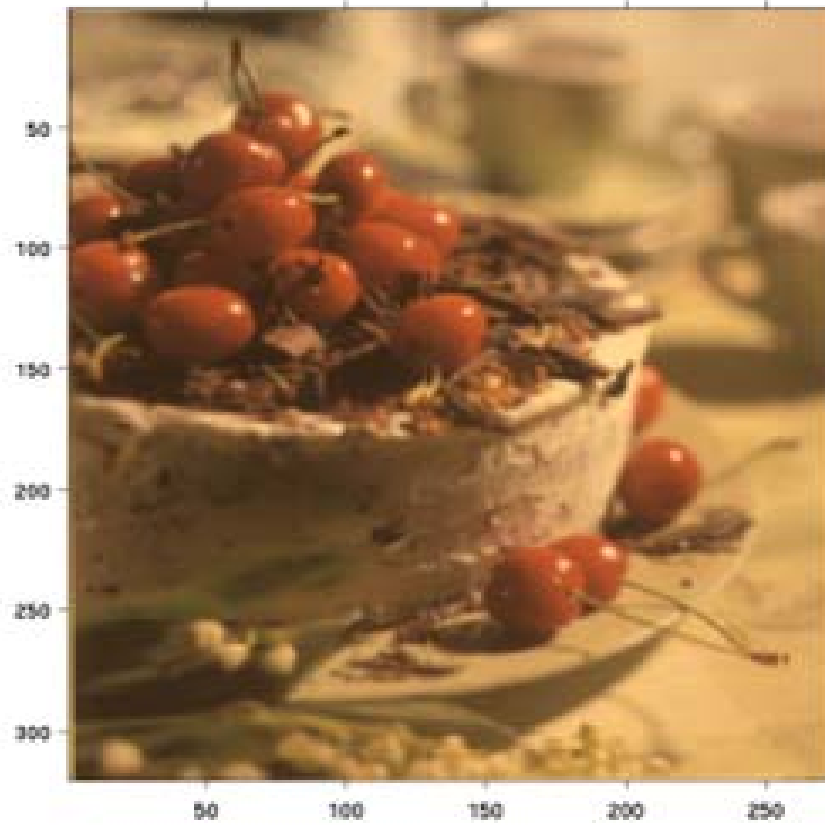
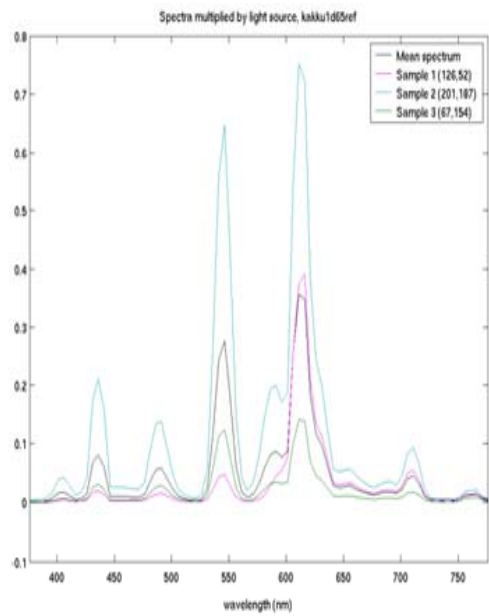
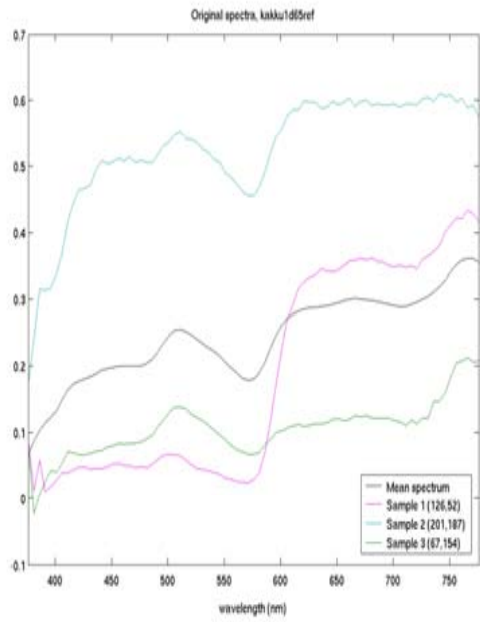
• F11



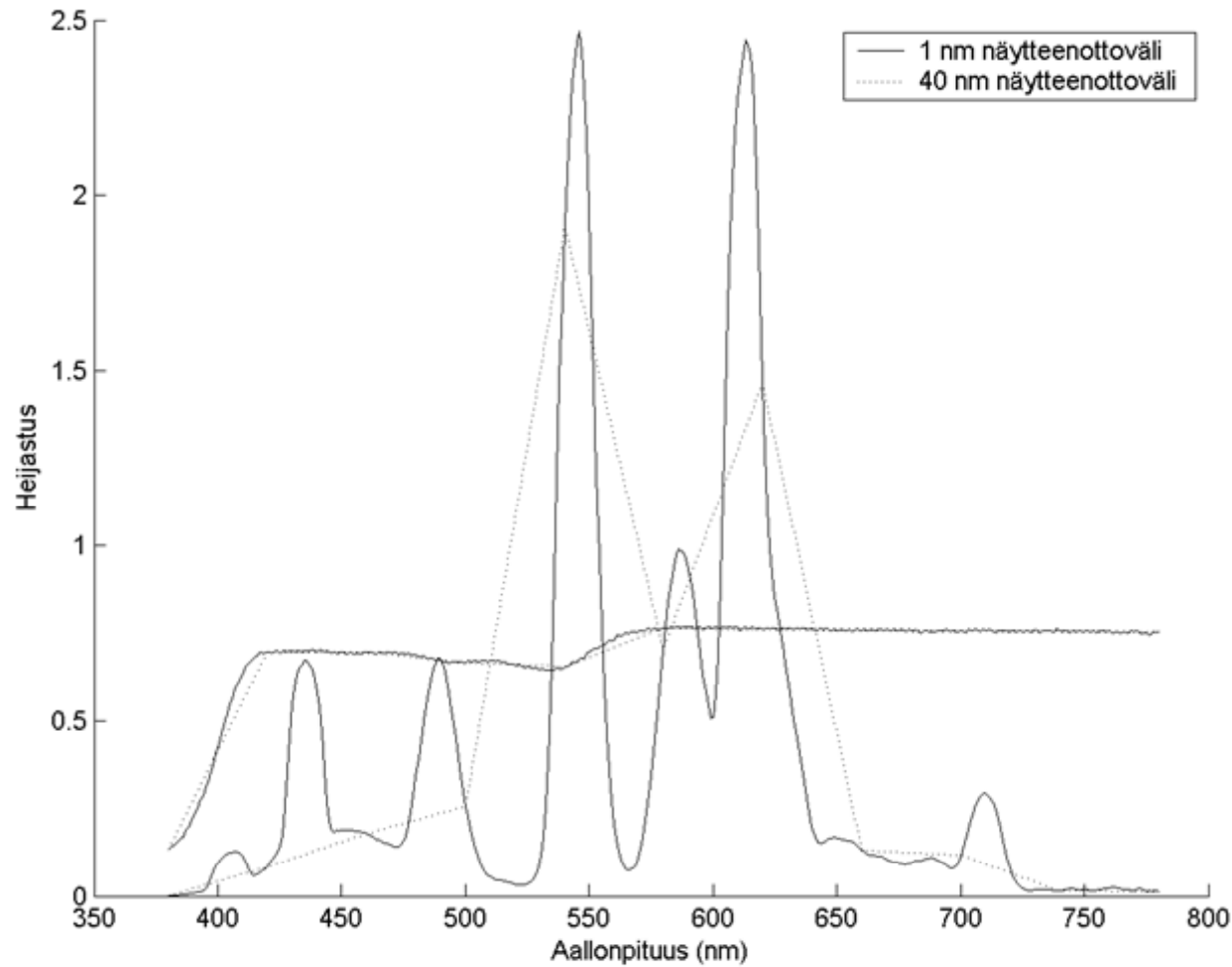
• A



• White LED



Spectral dependence on sampling



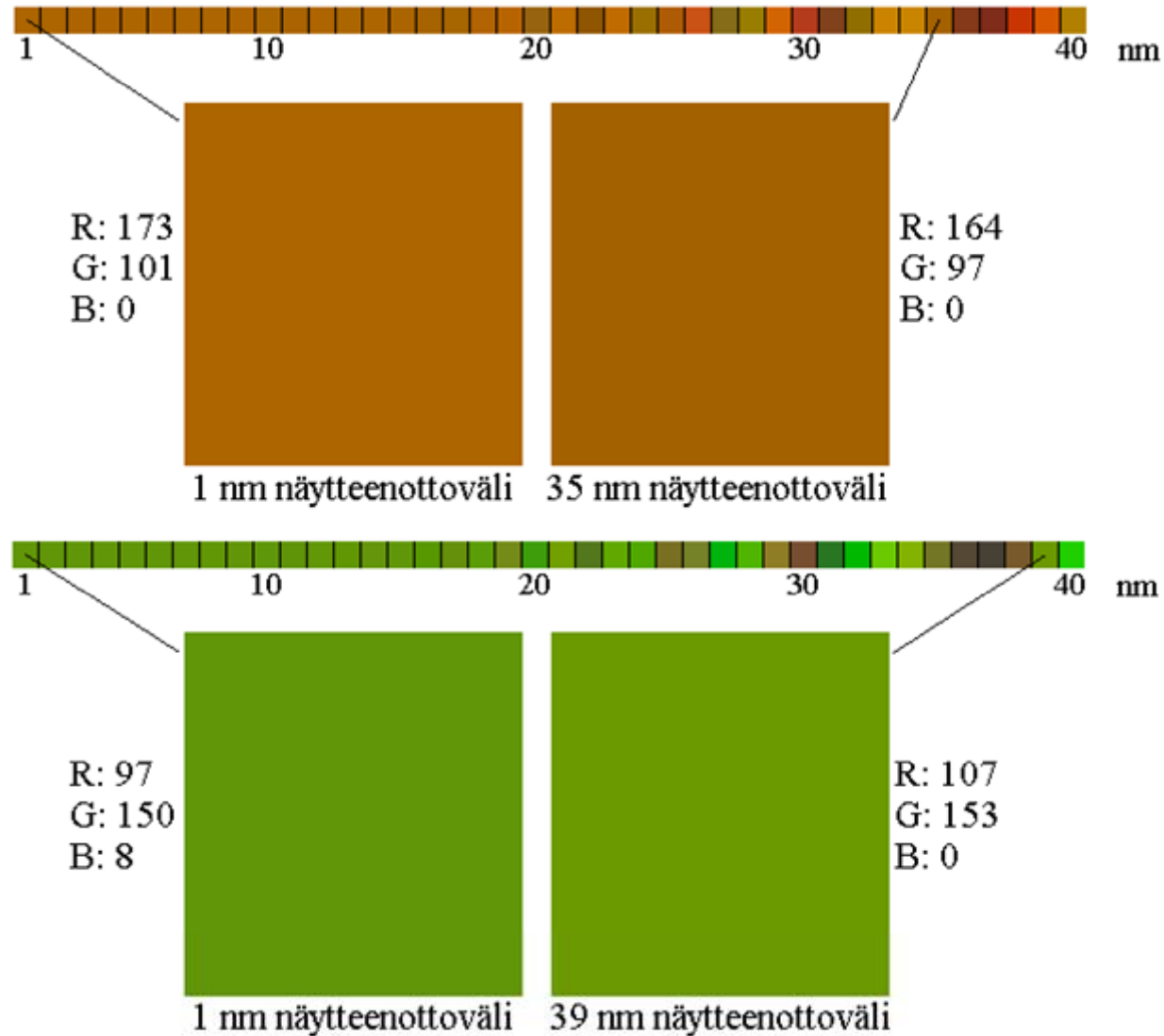
Munsell-sarjan värispektrin sRGB-esitys näytteenottovälin kasvaessa:



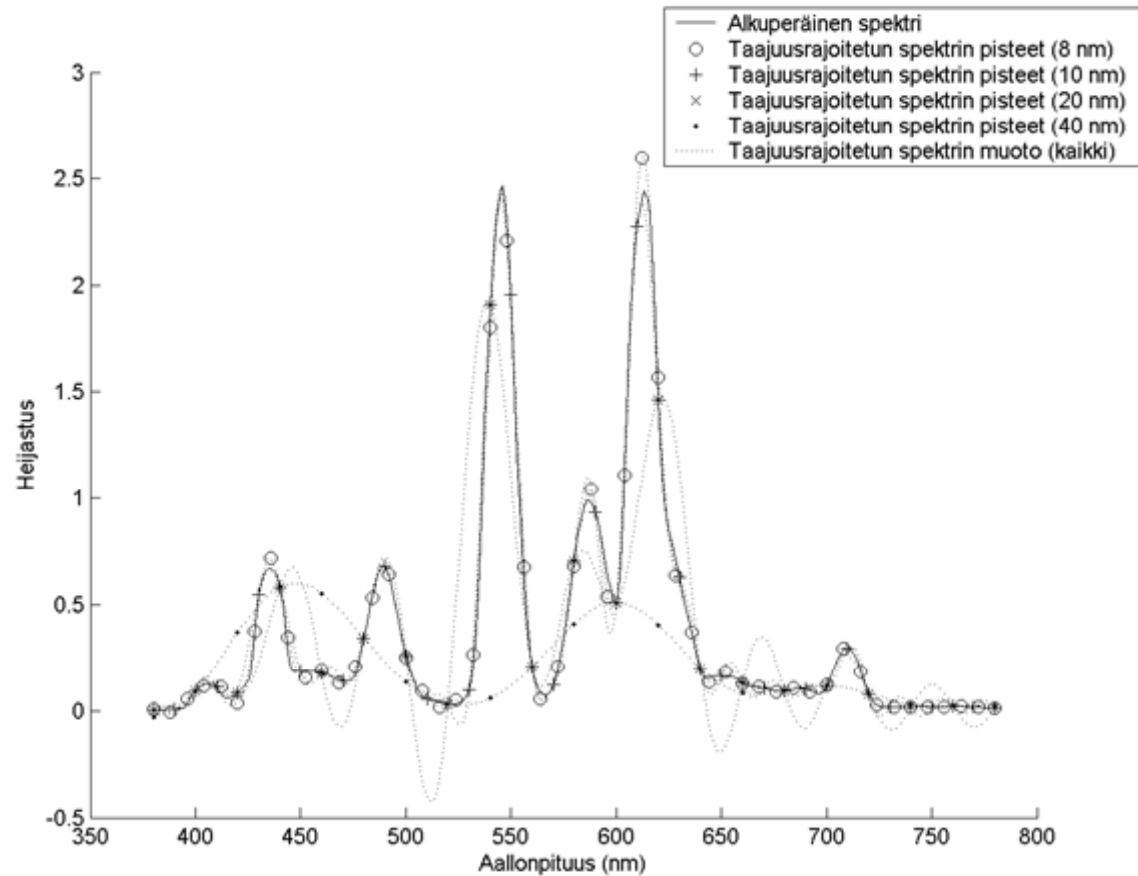
Munsell-sarjan värispektrin (valonlähteen kanssa) sRGB-esitys näytteenottovälin kasvaessa:



Color dependence on sampling



Change of RGB-values due to sampling



Alkuperäinen: RGB = (146, 75, 56)

Suoraan harvennettu:

8 nm: RGB = (145, 75, 55)

10 nm: RGB = (143, 75, 59)

20 nm: RGB = (126, 75, 63)

40 nm: RGB = (148, 101, 24)

Taajuusrajoitettu:

8 nm: RGB = (146, 74, 57)

10 nm: RGB = (143, 75, 59)

20 nm: RGB = (126, 75, 63)

40 nm: RGB = (96, 29, 82)







Device independent color representation

- polynomial approximation of spectrum from RGB
- kernel estimation of spectrum from RGB

- learning phase in the process
- training set is needed for parameter selection



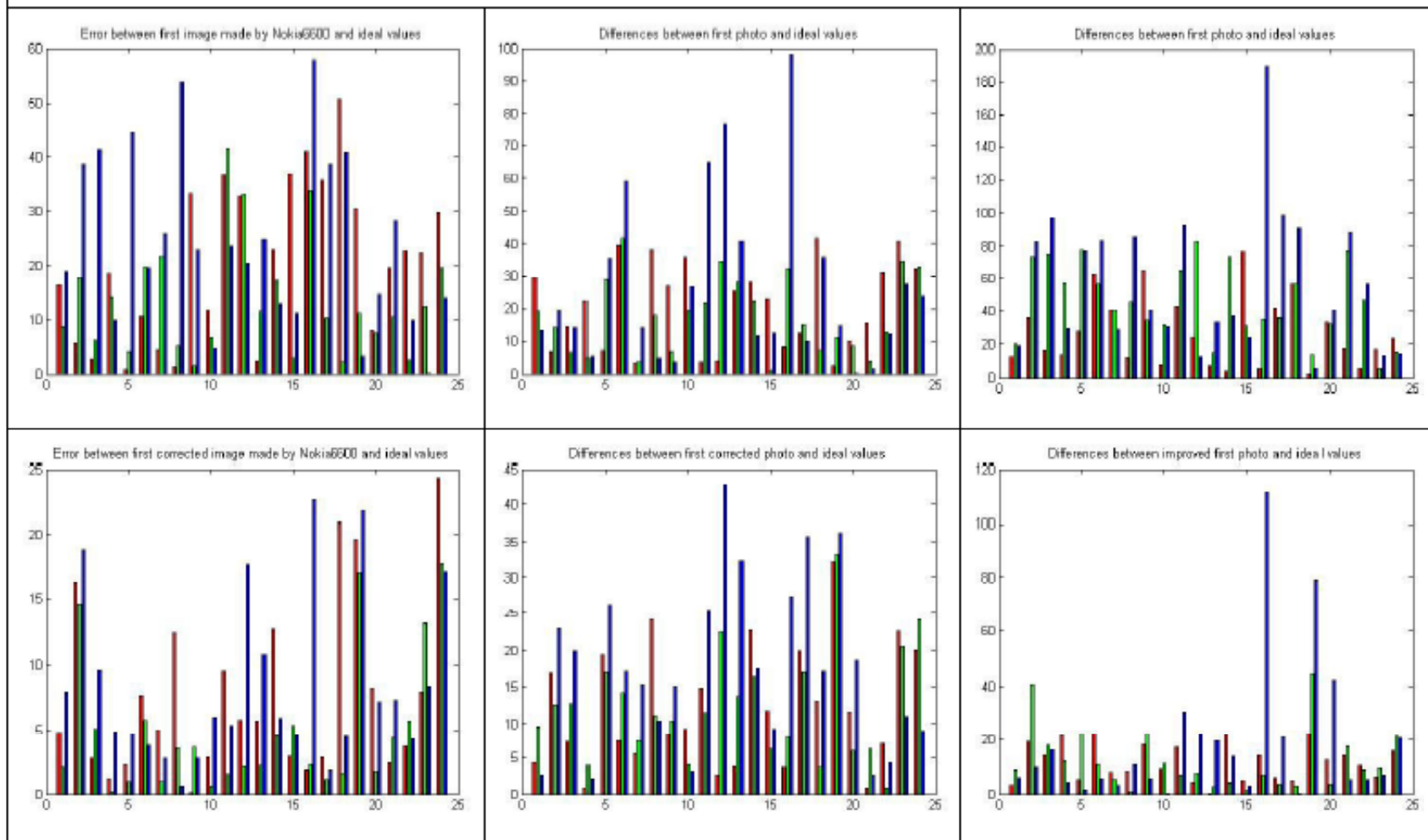
Some tests with mobile phones cameras

<i>Nokia 6600</i>	<i>Siemens S65</i>	<i>Samsung SGH-D500</i>
Original mobile phone images		
 <p data-bbox="376 906 680 925">DrehtagMasbeth® ColorChecker Color Resolution Chart</p>	 <p data-bbox="958 906 1263 925">DrehtagMasbeth® ColorChecker Color Resolution Chart</p>	 <p data-bbox="1541 906 1845 925">DrehtagMasbeth® ColorChecker Color Resolution Chart</p>
Images improved using 2 nd order polynomial model		
 <p data-bbox="376 1398 680 1417">DrehtagMasbeth® ColorChecker Color Resolution Chart</p>	 <p data-bbox="958 1398 1263 1417">DrehtagMasbeth® ColorChecker Color Resolution Chart</p>	 <p data-bbox="1541 1398 1845 1417">DrehtagMasbeth® ColorChecker Color Resolution Chart</p>

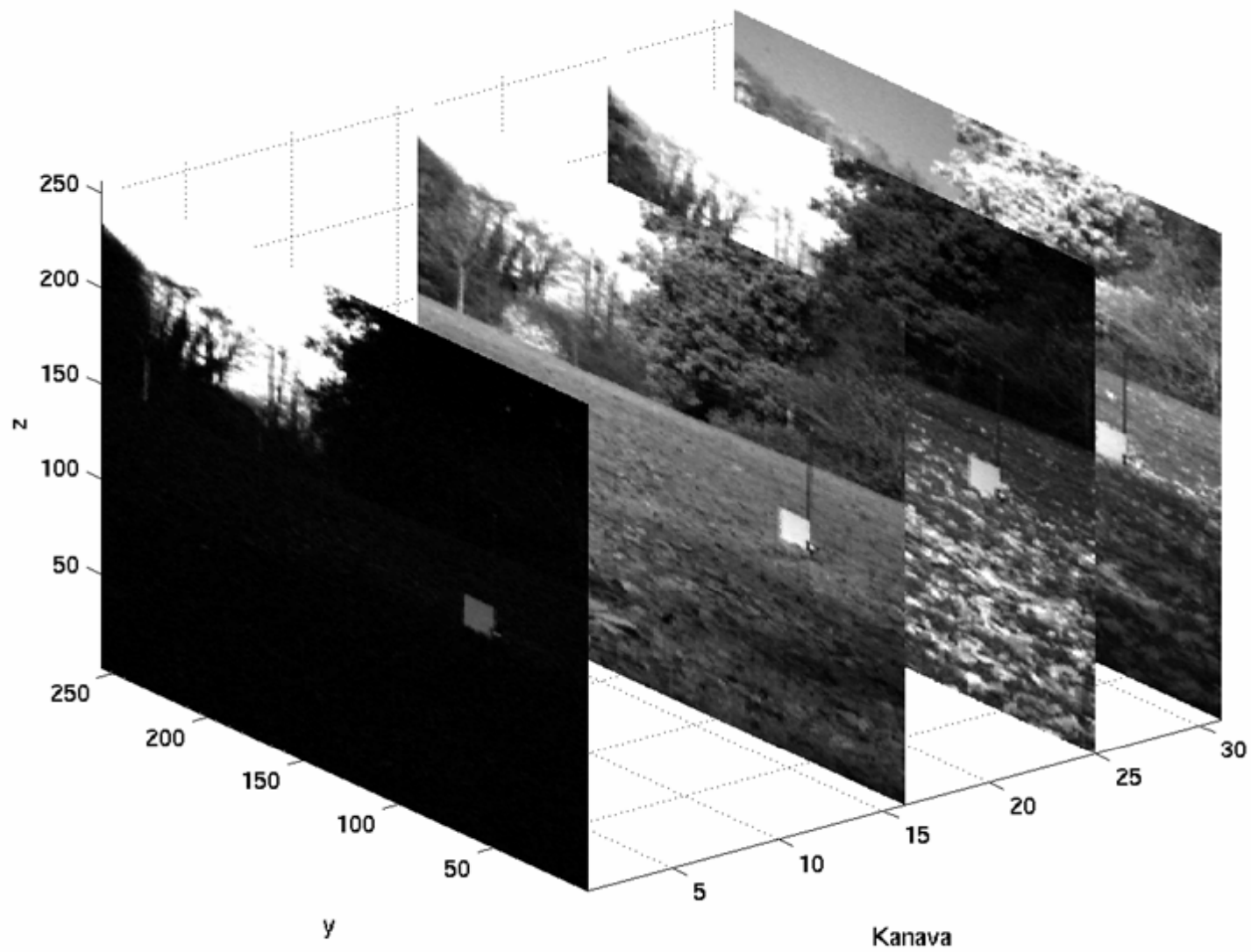
Some tests with mobile phones cameras

Error between RGB values of camera image and ideal sRGB values calculated from spectra.

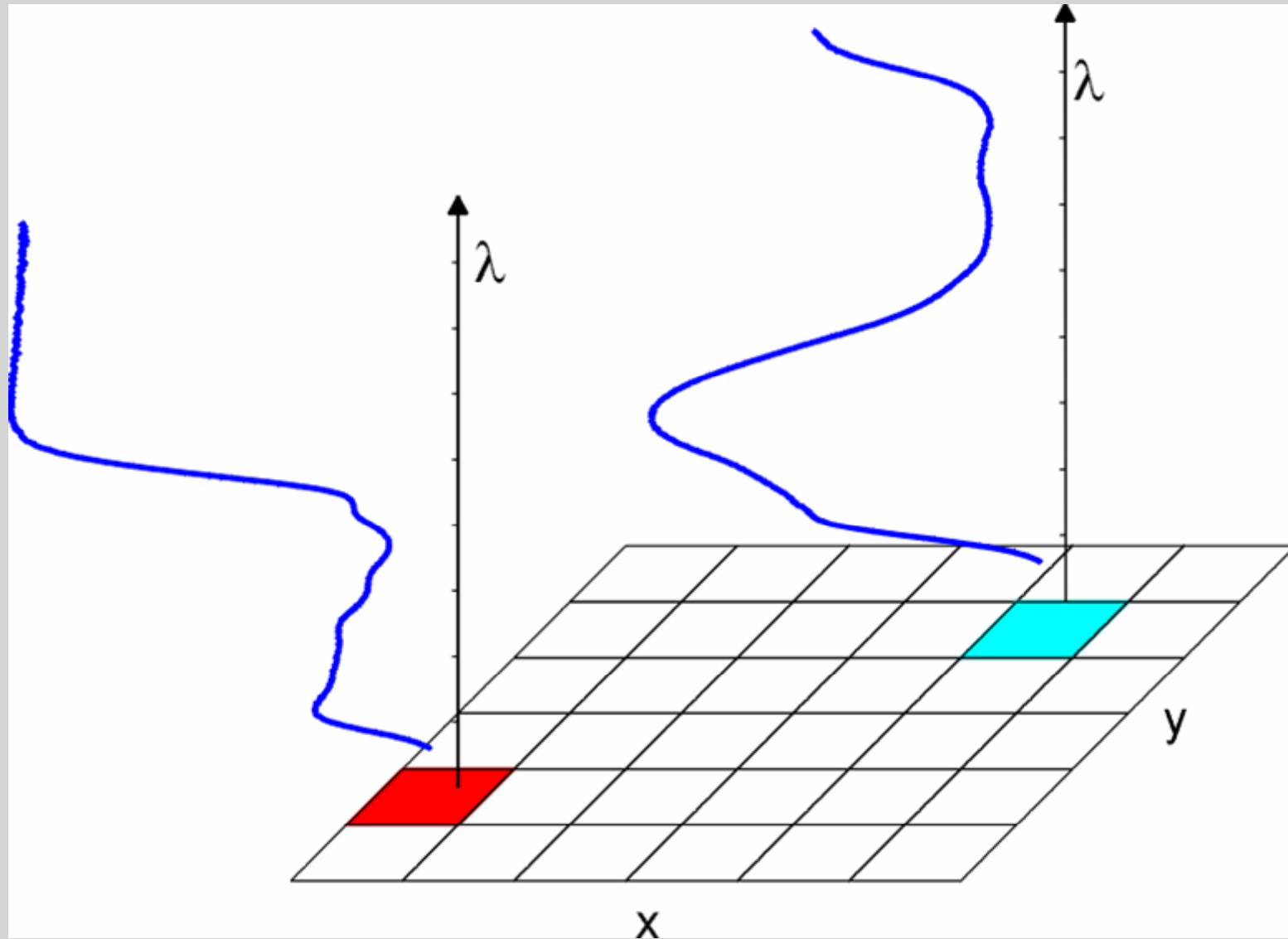
First row: error between the original image and ideal values.
Second row: error between the corrected image and ideal values.
Note that the scale of y-axis of diagrams varies between images.



Spectral component images



Spectral Image



Definitions

- Spectral image

An image, where each pixel is represented by a spectrum

- Hyperspectral

A term used for spectral images with large number of spectral components

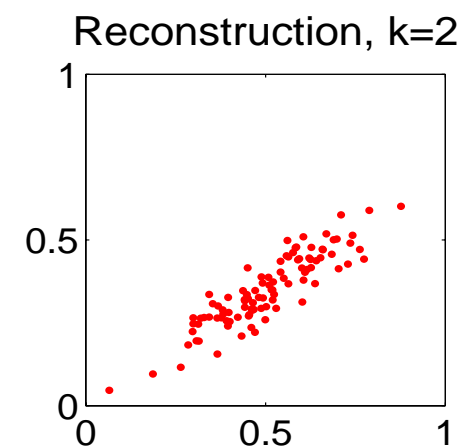
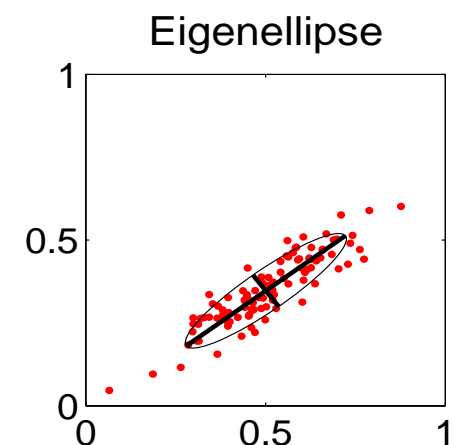
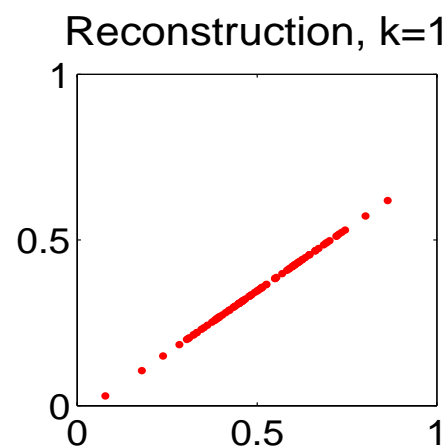
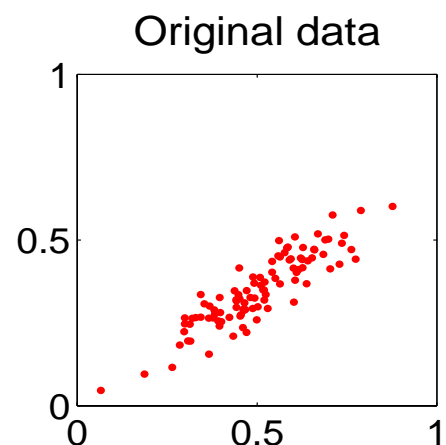
- Multispectral

- RGB-image

*spectrum in visible region,
three components*

Standard PCA. Example

- The first principal component is used when $k=1$
- The first and second principal components are used when $k=2$. Reconstruction is perfect

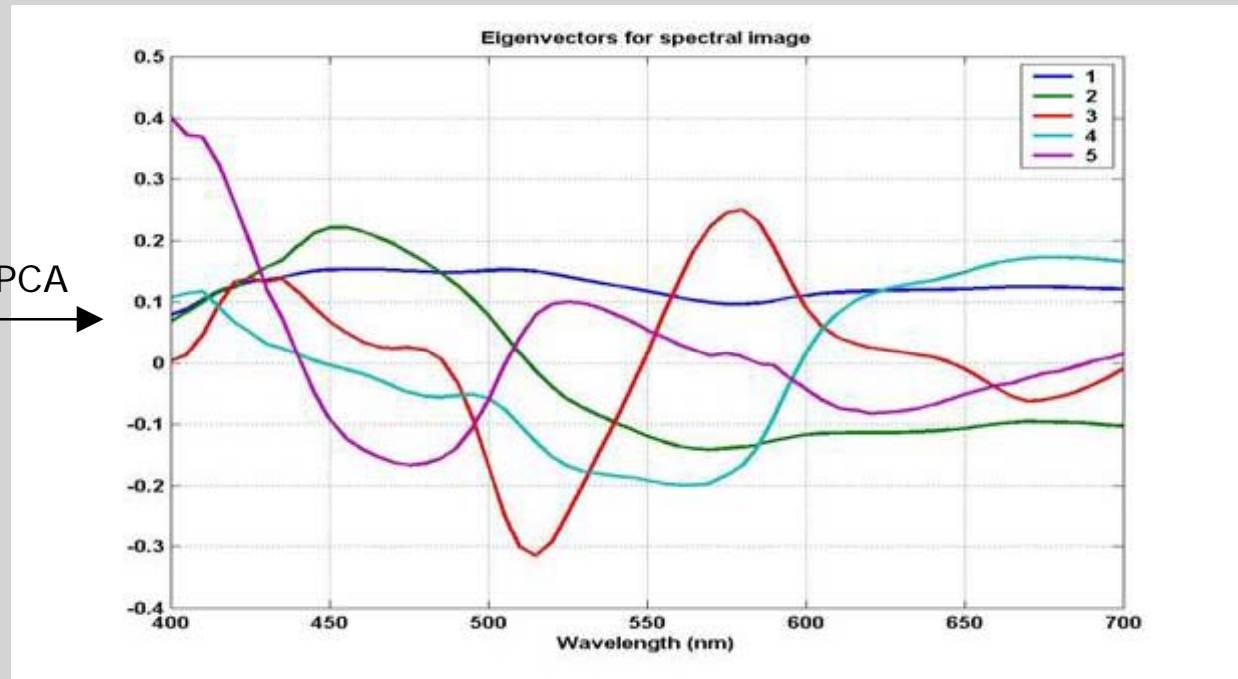


Component images of a spectral image



Spectral image as RGB-image

PCA
→



Inner-product images between the spectral image and eigenvectors:



1



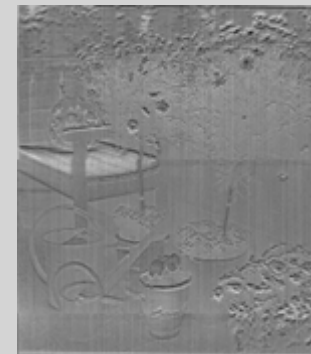
2



3



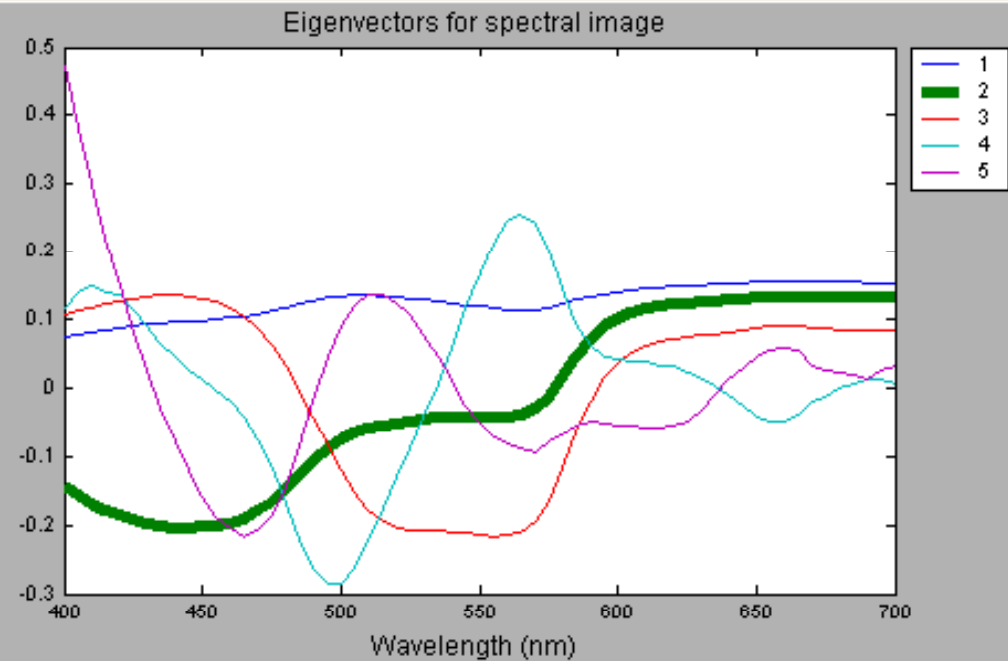
4



5

Principal Component Analysis

File Help



Load image

Wavelength
400:5:700

Change wavelength

Number of eigenvectors: 5

Update view

Fidelity 99.9937 %

Select images for reconstruction

Reset selections

Inner product images between spectral image and eigenvectors:

Images selected for reconstruction: All



1



2



3



4

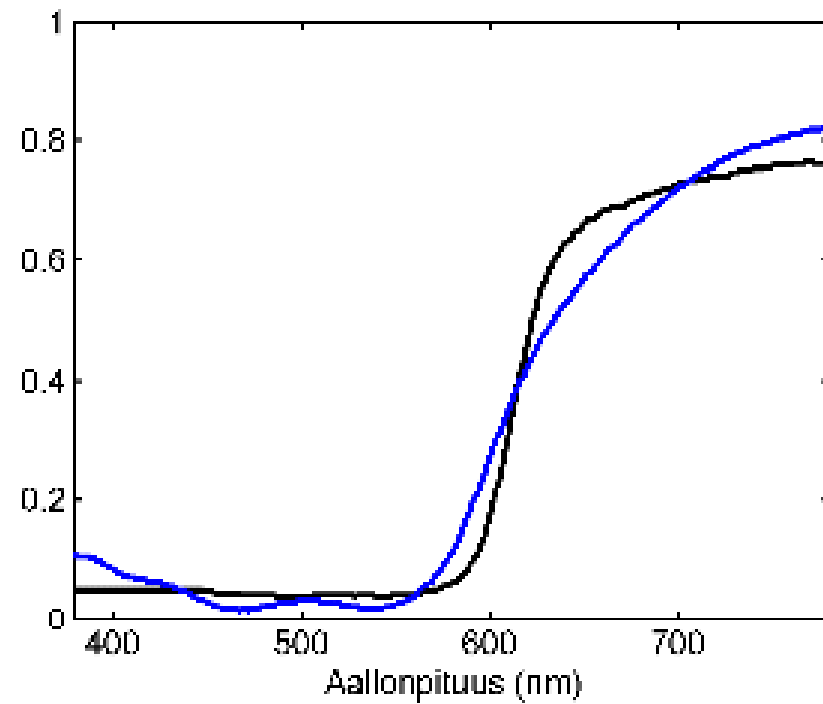
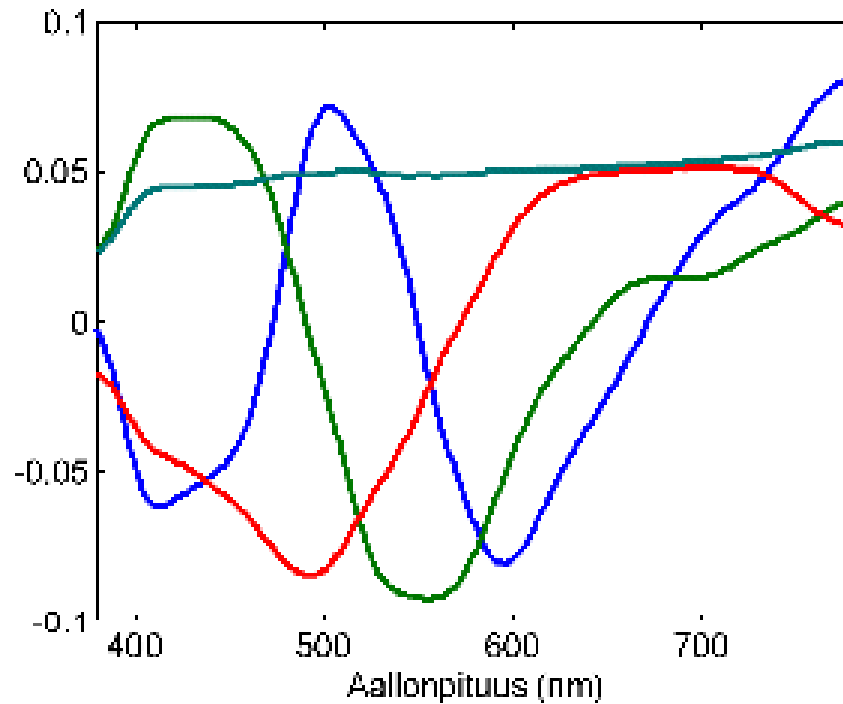


5

Inner product images

Compression errors

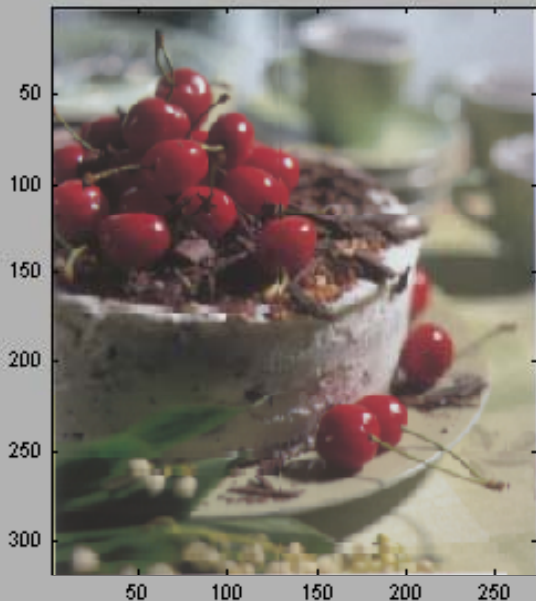
Reconstruction of the spectrum



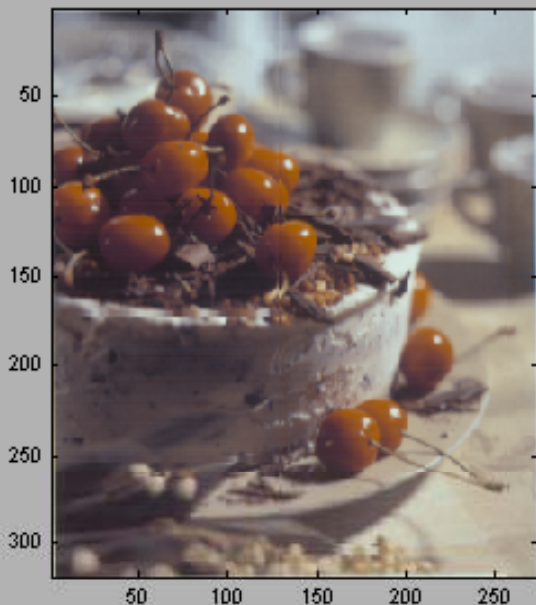
Principal Component Analysis

File Help

Original image (1)



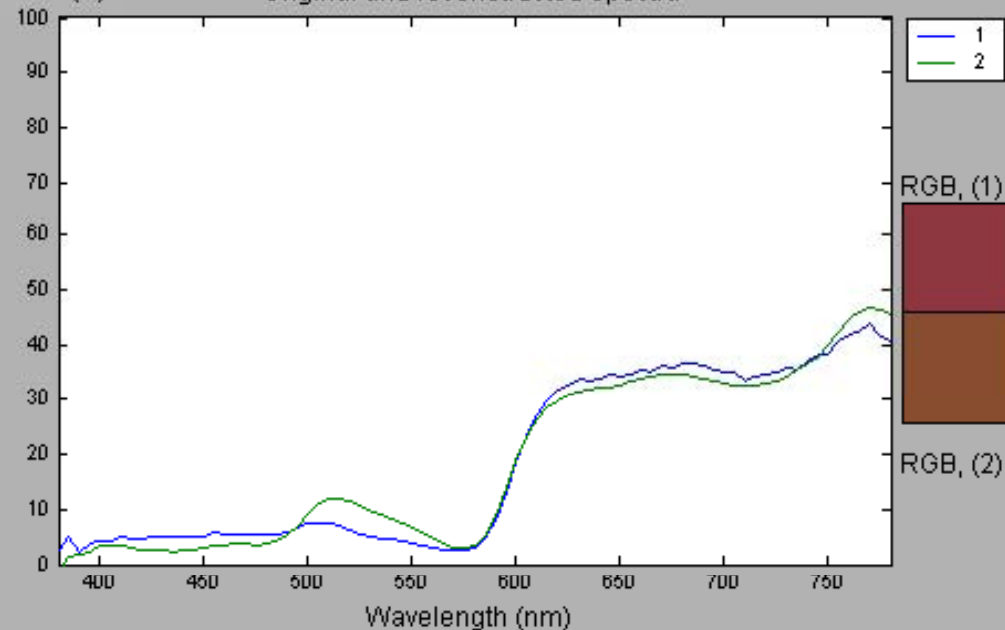
Reconstructed image (2)



Inner product images

Compression errors

Value (%) Original and reconstructed spectra



Compression Rate	26.98	pixel 97,111 :	
Average errors:		Errors of selected spectrum:	
Δ E	7.54	Δ E	21.5
Δ E S-CIELAB	6.35	Δ E S-CIELAB	5.34
Peak Signal-to-Noise Ratio	34.3	Peak Signal-to-Noise Ratio	32.42
Mean Square Error	0.00037	Mean Square Error	0.00057

Zoom image

Original size

Actual pixels

Select light source:

- A
- C
- D50
- D65

Select system:

- 1931
- 1964

Spectrum type:

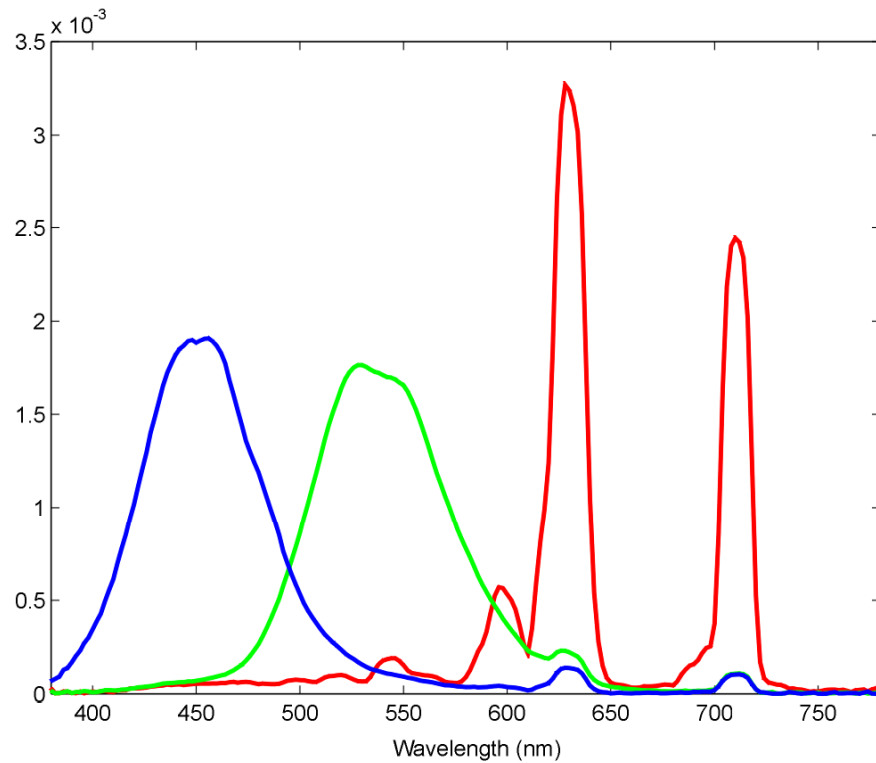
- Reflectance
- Relative radiance

Select other source

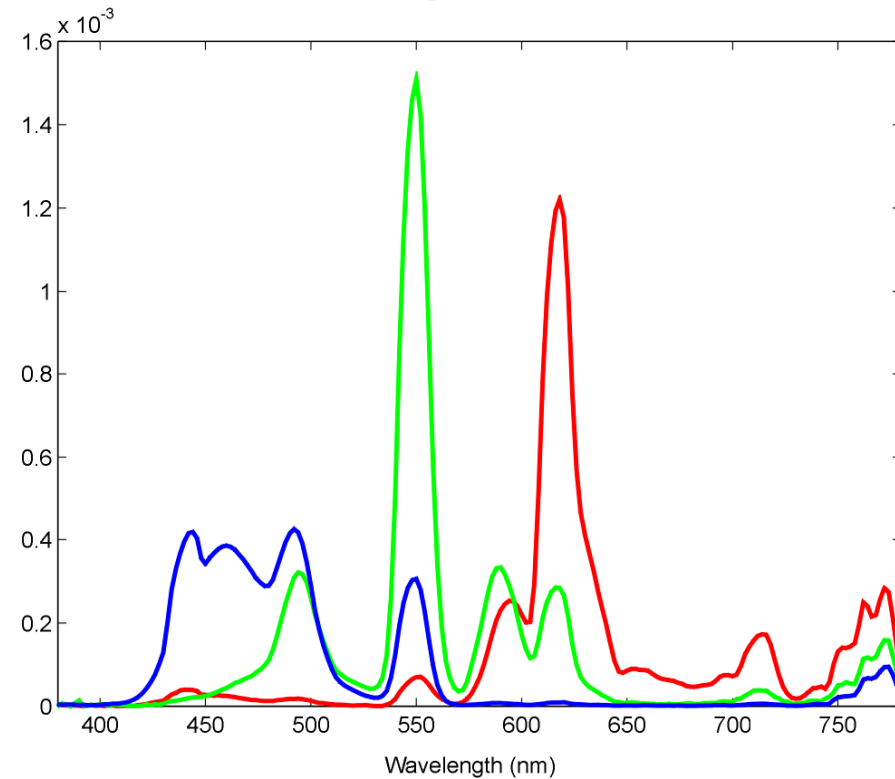


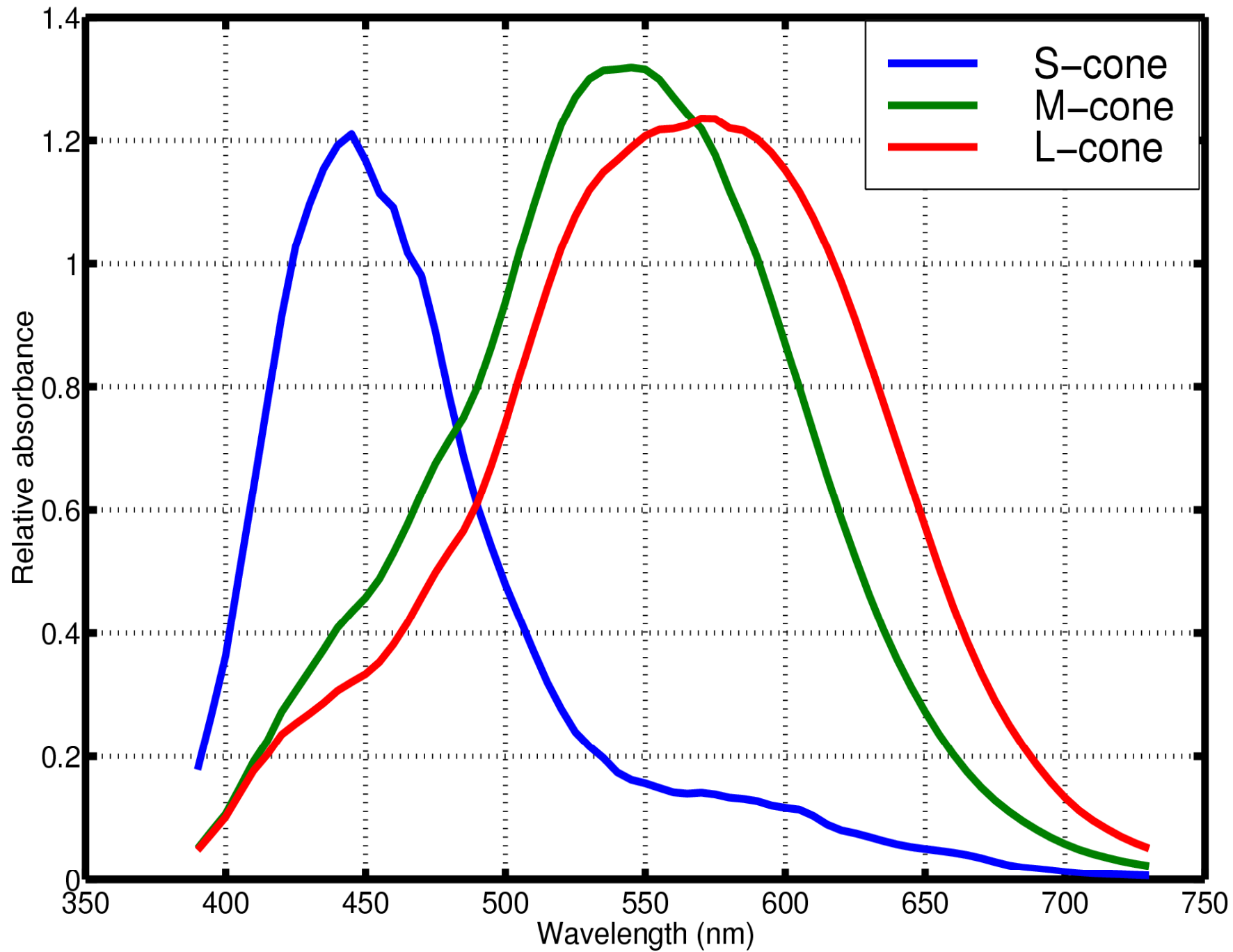
Display characteristics

CRT primaries

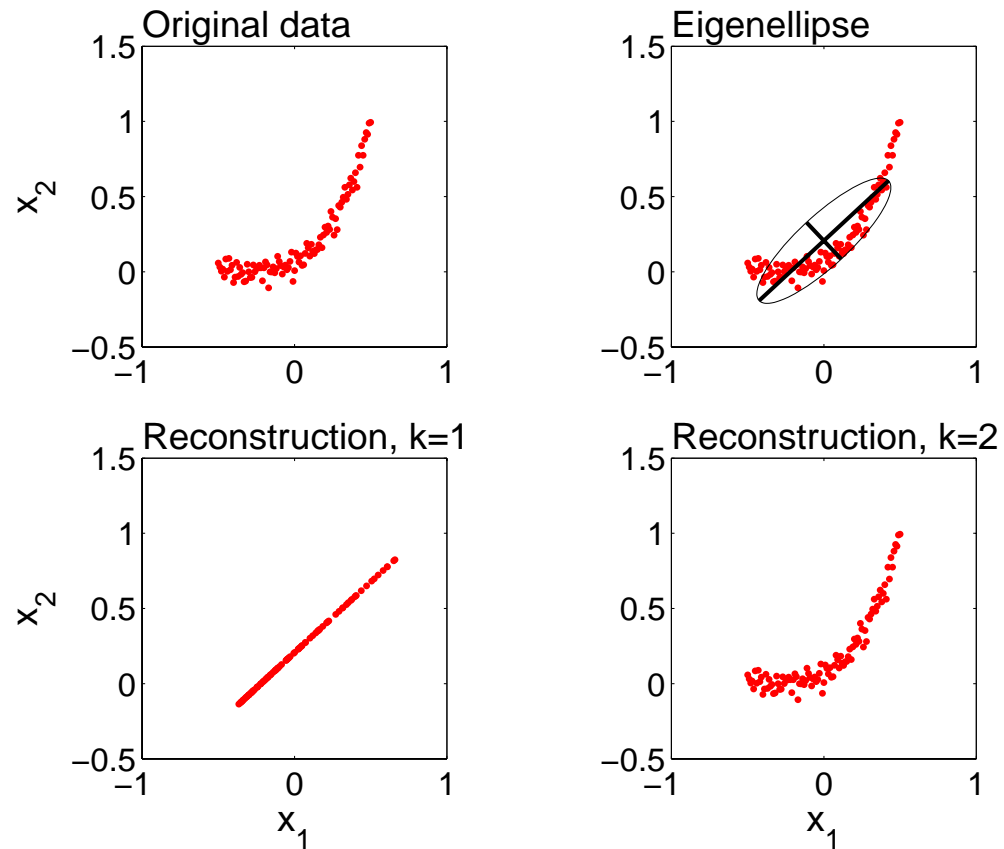


LCD primaries

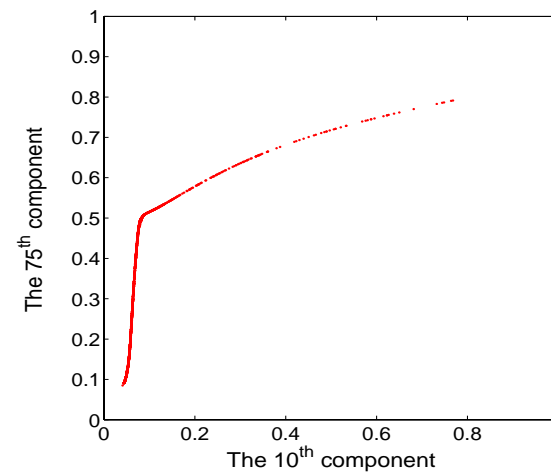
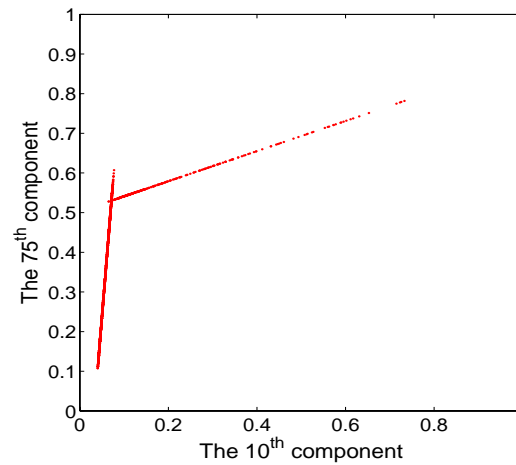
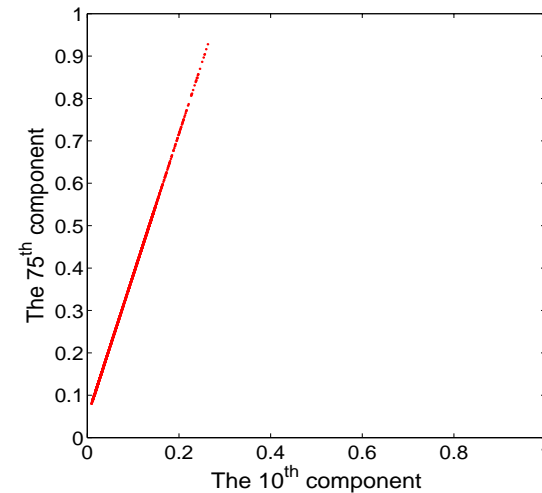
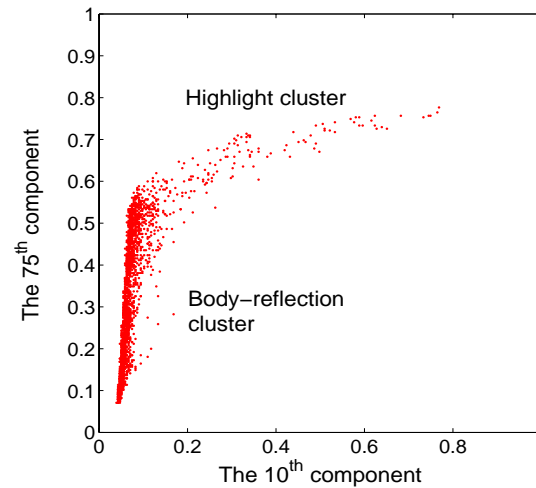




Nonlinear data



Spectral color analysis

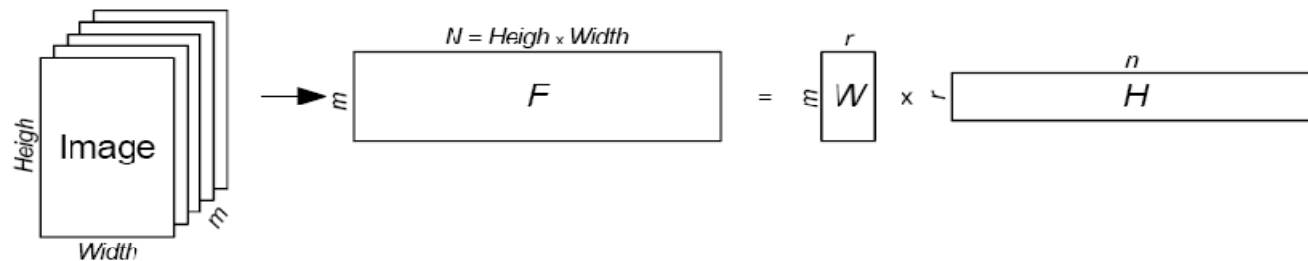


Non-negative Matrix Factorization

Given a data matrix $F = \{F_{ij}\}_{m \times n}$, non-negative matrix factorization refers to the decomposition of the matrix F into matrices W and H of size $m \times r$ and $r \times n$, respectively, such that:

$$F = WH$$

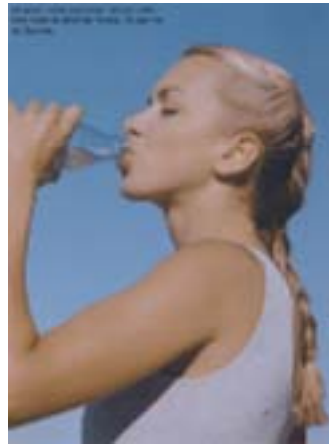
Where the elements in W and H are all positive values. From this decomposition, a reduced representation is achieved by choosing r such that $r \ll n$ and $r \ll m$.



Results



$r = 1;$



$r = 2;$



$r = 3;$



$r = 5;$



$r = 81;$



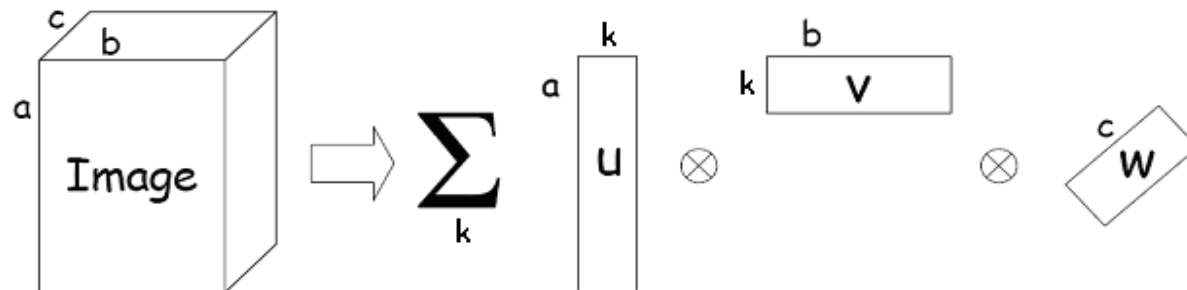
original



Non-negative Tensor Factorization

- The basic approach of NTF is to find a solution for the problem:

$$\min_{u^m, v^m, w^m \geq 0} \left\| G - \sum_{m=1}^k u^m \otimes v^m \otimes w^m \right\|$$



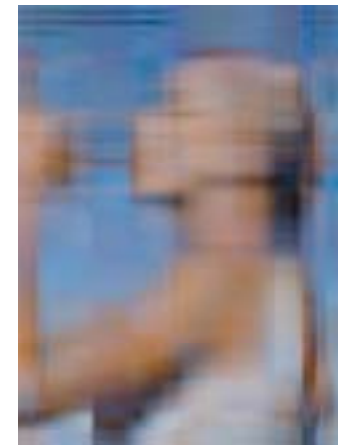
Results



$m = 1;$



$m = 5;$



$m = 10;$



$m = 50;$



$m = 100;$

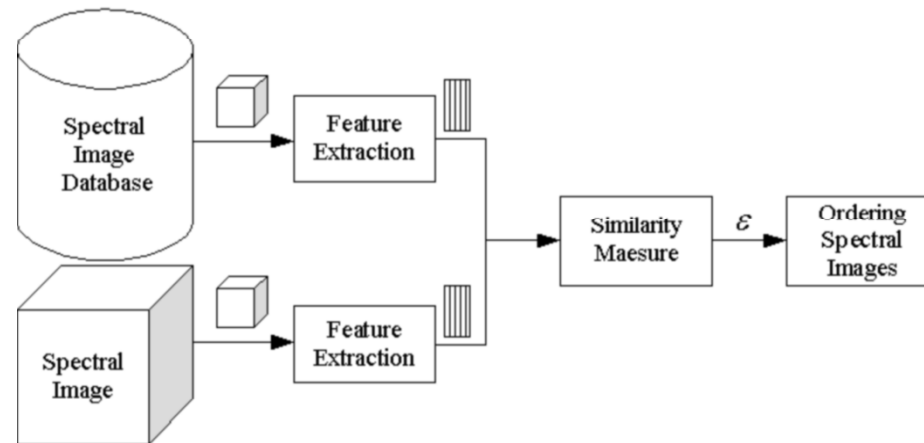


original



Searching Method

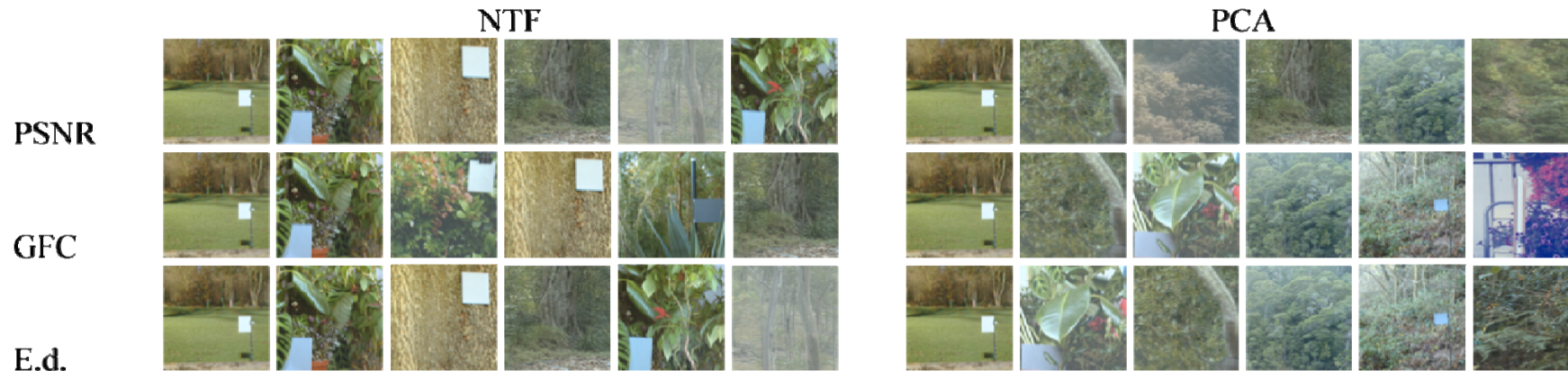
- NTF and PCA take spectra domain basis from each spectral image. Those basis defines as spectral color features.
- Similarity measures (Euclidian distance, goodness of fit coefficient (GFC) and peak signal-to-noise ratio (PSNR)) are calculated between spectra color features.



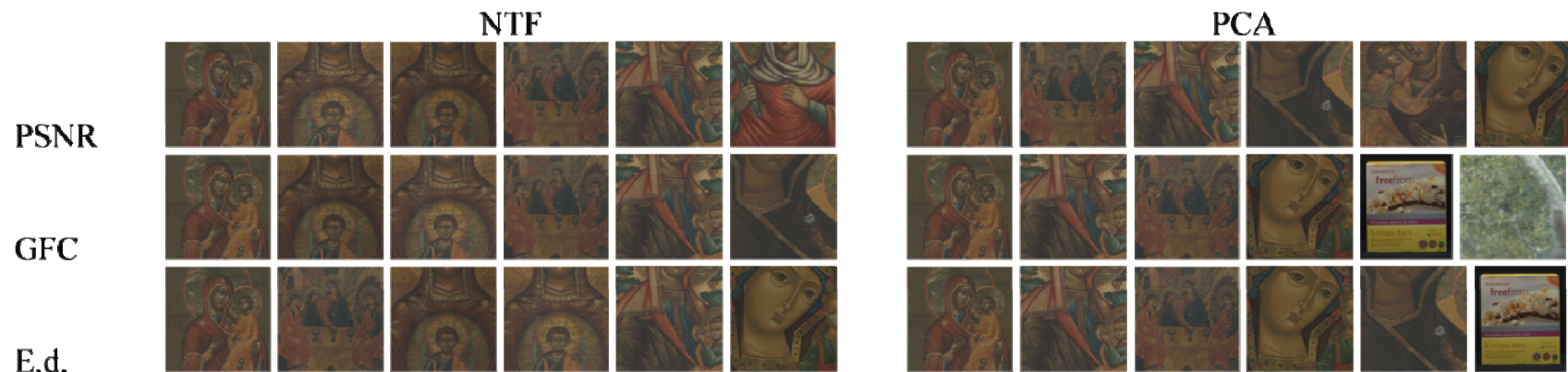
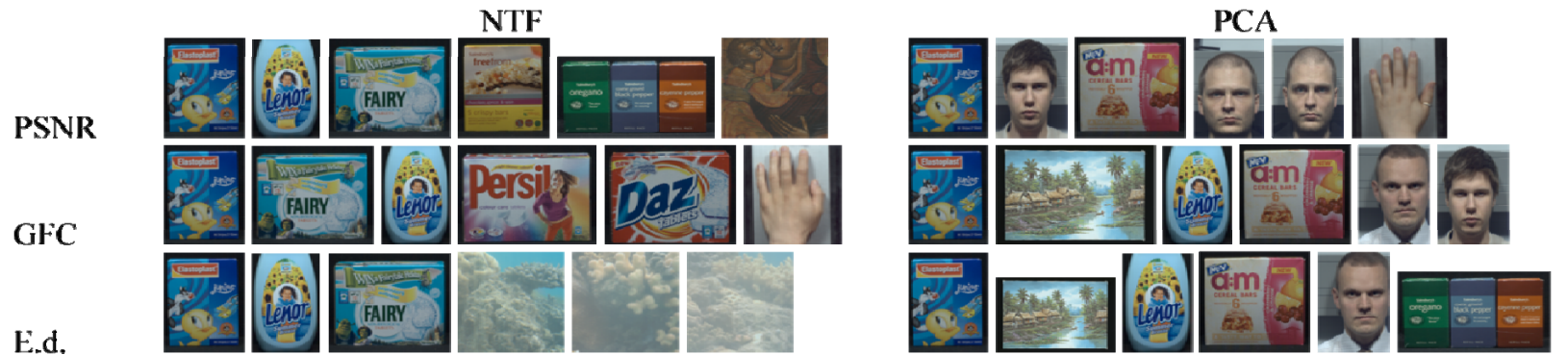
Experiments



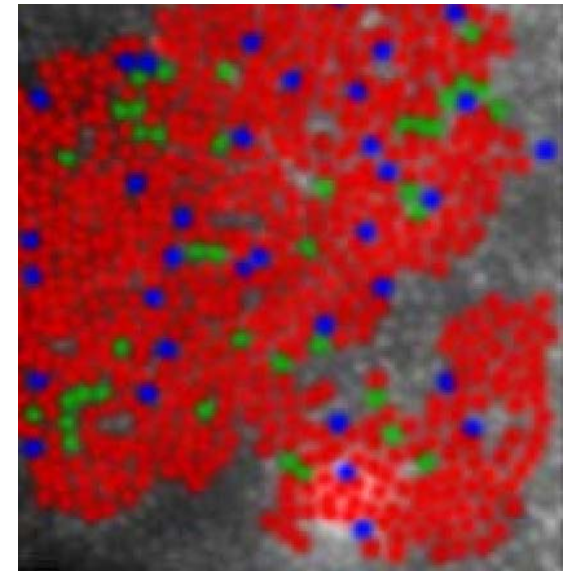
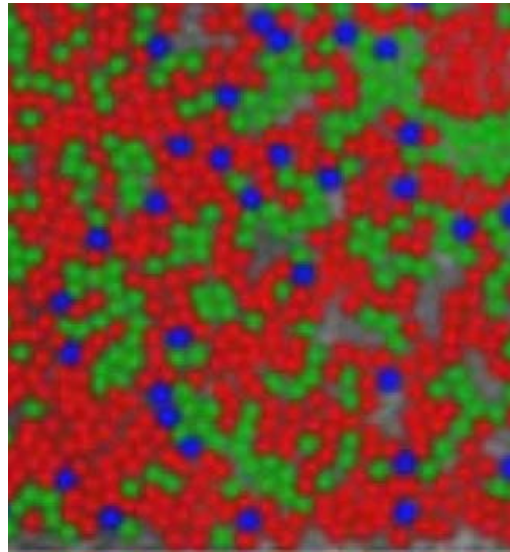
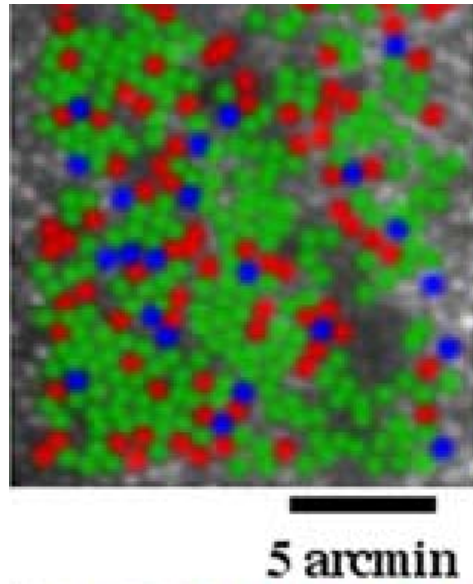
Results



Results



Distribution of Cone Cells in Human Eye



Reference: Hofer *et al.*, Organization of the Human Trichromatic Cone Mosaic. *J. Neurosci.* (2005)
